

Introduction to fractional calculus

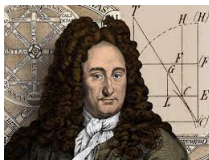
Jacky CRESSON

Université de Pau et Pays des pays de l'Adour

SFM 2022 - Nantes



Fractional calculus ? Beginning with a curious question

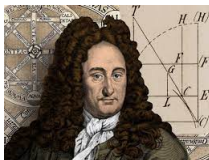


1695...Leibniz just invented the notation

$$\frac{d^n f}{dt^n}$$

for the n -th derivative of a function f .

Fractional calculus ? Beginning with a curious question



1695...Leibniz just invented the notation

$$\frac{d^n f}{dt^n}$$

for the n -th derivative of a function f .



L'Hopital receives the letter of Leibniz and writes

What if n be $1/2$?

Why not ?

Leibniz answer:

Why not ?

Leibniz answer:

possible with infinite series.... "one day, useful consequences will be drawn."

Why not ?

Leibniz answer:

possible with infinite series...."one day, useful consequences will be drawn."

1697 Leibniz write to Wallis that some functional equations can be solved using fractional differential calculus.

Why not ?

Leibniz answer:

possible with infinite series...."one day, useful consequences will be drawn."

1697 Leibniz write to Wallis that some functional equations can be solved using fractional differential calculus.

Euler, Lagrange, Riemann, Liouville, Abel, etc

Why not ?

Leibniz answer:

possible with infinite series...."one day, useful consequences will be drawn."

1697 Leibniz write to Wallis that some functional equations can be solved using fractional differential calculus.

Euler, Lagrange, Riemann, Liouville, Abel, etc

Classical reference: S. Samko, A. Kilbas and O. Marichev, *Fractional integrals and derivatives: theory and applications*, Gordon and Beach, Yverdon, 1993.

The algebraic problem

Finding an operator D^α , $\alpha \in \mathbb{R}^+$, which is an extension of the classical derivative, i.e. satisfying for $n \in \mathbb{N}$

$$D^n[f] = \frac{d^n f}{dt^n}. \quad (1)$$

The algebraic problem

Finding an operator D^α , $\alpha \in \mathbb{R}^+$, which is an extension of the classical derivative, i.e. satisfying for $n \in \mathbb{N}$

$$D^n[f] = \frac{d^n f}{dt^n}. \quad (1)$$

We want also that all these operators are **linear**

The algebraic problem

Finding an operator D^α , $\alpha \in \mathbb{R}^+$, which is an extension of the classical derivative, i.e. satisfying for $n \in \mathbb{N}$

$$D^n[f] = \frac{d^n f}{dt^n}. \quad (1)$$

We want also that all these operators are **linear** satisfies a semi-group property:

$$D^\alpha \circ D^\beta = D^{\alpha+\beta}. \quad (2)$$

Iterated left antiderivative

Let $I = [a, b]$ be an interval and $f : I \rightarrow \mathbb{R}^d$ be a sufficiently smooth function. We denote by $I_{a+}^1[f]$ the antiderivative of f vanishing at $t = a$, i.e.

$$\forall t \in I, \quad I_{a+}^1[f](t) = \int_a^t f(s) ds. \quad (3)$$

We denote by I_{a+}^k the operator defined for all $k \in \mathbb{N}^*$ by

$$I_{a+}^k = I_{a+}^1 \circ \dots \circ I_{a+}^1 \quad (k \text{ times}). \quad (4)$$

Using the Fubini's theorem, we have

$$\begin{aligned} I_{a+}^2[f](t) &= \int_a^t \left(\int_a^s f(u) du \right) ds = \int_a^t \left(\int_u^t ds \right) f(u) du, \\ &= \int_a^t (t - u) f(u) du. \end{aligned} \quad (5)$$

We can prove by induction and the Fubini theorem that for all $t \in I$, we have

$$I_{a+}^k[f](t) = \frac{1}{(k-1)!} \int_a^t (t-u)^{k-1} f(u) du. \quad (6)$$

For every $k \in \mathbb{N}^*$, the quantity $I_{a+}^k[f]$ is called the **left integral** with inferior limit a of order k of f .

Algebraic definition of iterated antiderivative

The left integral of order k with inferior limit a of f is the unique solution g of the following problem

$$\forall 0 \leq n \leq k - 1, \quad g^{(n)}(a) = 0, \quad g^{(k)} = f. \quad (7)$$

The terminology for left comes from the fact that the integral is evaluated using value of $f(s)$ on the left hand side, i.e. with $s < t$.

Iterated derivatives

The k -th derivative of f , satisfies for all $t \in I$,

$$\left(\frac{d}{dt}\right)^k [f] = \left(\frac{d}{dt}\right)^{k+1} [I_{a+}^1[f]], \quad (8)$$

and

$$\left(\frac{d}{dt}\right)^k [f](t) - \left(\frac{d}{dt}\right)^k [f](a) = I_{a+}^1 \left[\left(\frac{d}{dt}\right)^{k+1} [f] \right] (t). \quad (9)$$

Right iterated integrals

Let $b \in \mathbb{R}$ and $f : I \rightarrow \mathbb{R}$ be a sufficiently smooth function. We denote by $I_{b-}^1[f]$ the minus antiderivative of f vanishing at $t = b$, i.e. for all $t \in I$,

$$I_{b-}^1[f](t) = \int_t^b f(s) ds. \quad (10)$$

For every $k \in \mathbb{N}^*$, we denote by $I_{b-}^k = I_{b-}^1 \circ \dots \circ I_{b-}^1$ (k -times). We easily prove that for all $t \in I$, we have

$$I_{b-}^k[f](t) = \frac{1}{(k-1)!} \int_t^b (u-t)^{k-1} f(u) du. \quad (11)$$

The quantity $I_{b-}^k[f]$ is usually called the **right integral** of order k with superior limit b of f .

Right iterated derivatives

The k -th antiderivative satisfies for all $t \in I$ the relations

$$\left(-\frac{d}{dt}\right)^k [f] = \left(-\frac{d}{dt}\right)^{k+1} [I_{b-}^1[f]], \quad (12)$$

and

$$\left(-\frac{d}{dt}\right)^k [f](t) - \left(-\frac{d}{dt}\right)^k [f](b) = I_{b+}^1 \left[\left(-\frac{d}{dt}\right)^{k+1} [f] \right](t). \quad (13)$$

Main strategy

The basic idea behind fractional integrals and derivatives is that having a generalization of the left (resp. right) integral of order k for positive real values of k , then one can obtain a generalization of the notion of k -th derivative of f using:

Main strategy

The basic idea behind fractional integrals and derivatives is that having a generalization of the left (resp. right) integral of order k for positive real values of k , then one can obtain a generalization of the notion of k -th derivative of f using:
relations (8) leading to the left fractional Riemann-Liouville derivative

Main strategy

The basic idea behind fractional integrals and derivatives is that having a generalization of the left (resp. right) integral of order k for positive real values of k , then one can obtain a generalization of the notion of k -th derivative of f using:

relations (8) leading to the left fractional Riemann-Liouville derivative

relations (9) leading to the left fractional Caputo derivative respectively.

Main strategy

The basic idea behind fractional integrals and derivatives is that having a generalization of the left (resp. right) integral of order k for positive real values of k , then one can obtain a generalization of the notion of k -th derivative of f using:

relations (8) leading to the left fractional Riemann-Liouville derivative

relations (9) leading to the left fractional Caputo derivative respectively.

The right analogue is also possible.

Left Riemann-Liouville fractional integrals

The **Gamma function of Euler** denoted by Γ and defined for all $\alpha > 0$ by

$$\Gamma(\alpha) = \int_0^{+\infty} s^{\alpha-1} e^{-s} ds. \quad (14)$$

We have for all $k \in \mathbb{N}^*$ that $\Gamma(k) = (k-1)!$.

Left Riemann-Liouville fractional integrals

The **Gamma function of Euler** denoted by Γ and defined for all $\alpha > 0$ by

$$\Gamma(\alpha) = \int_0^{+\infty} s^{\alpha-1} e^{-s} ds. \quad (14)$$

We have for all $k \in \mathbb{N}^*$ that $\Gamma(k) = (k-1)!$.

The **Riemann-Liouville α -fractional integrals**, $\mathbb{R} \ni \alpha > 0$, for $f : [a, b] \mathbb{R}^d$, $d \in \mathbb{N}$, a $AC^2([a, b])$ function and $[a, b] \subset \mathbb{R}$, $0 \leq a < b$:

$$\begin{aligned} I_-^\alpha f(t) &= \frac{1}{\Gamma(\alpha)} \int_a^t (t-\tau)^{\alpha-1} f(\tau) d\tau, \quad t \in (a, b], \\ I_+^\alpha f(t) &= \frac{1}{\Gamma(\alpha)} \int_t^b (\tau-t)^{\alpha-1} f(\tau) d\tau, \quad t \in [a, b), \end{aligned} \quad (15)$$

We set $I_-^0 f = I_+^0 f = f$.

Example

The left fractional integral of Riemann-Liouville for the function $f(t) = (t - a)^\beta$ with $\beta > -1$. We have

$$I_+^\alpha[f](t) = \frac{\Gamma(\beta + 1)}{\Gamma(\beta + \alpha + 1)}(t - a)^{\beta + \alpha}, \quad (16)$$

for every $t \in [a, +\infty[$ if $\beta + \alpha \geq 0$ and $t \in]a, +\infty[$ if $\beta + \alpha < 0$.

Riemann-Liouville fractional derivatives

Restricting to $\alpha \in [0,1]$, we obtained what is called the Riemann-Liouville α -fractional derivatives:

$$\begin{aligned} D_-^\alpha[f] &= \frac{d}{dt} [I_-^{1-\alpha}[f]] , , \\ D_+^\alpha[f] &= -\frac{d}{dt} [I_+^{1-\alpha}[f]] . \end{aligned} \tag{17}$$

It is easy to see that $D_-^0 f = D_+^0 f = f$, whereas it can be proven that

$$D_-^1 f = -D_+^1 f = df/dt. \tag{18}$$

Some examples

The left fractional Riemann-Liouville derivative of a constant is not zero. Indeed, we have

$$D_+^\alpha[c] = \frac{c}{\Gamma(1-\alpha)}(t-a)^{-\alpha}, \quad (19)$$

for $\alpha \in]0, 1[$ and $t > a$. This properties in particular implies that a geometric interpretation of the fractional derivative is not possible. Indeed, from a geometrical view point, for an arbitrary constant $c \in \mathbb{R}$, the fonction f and $f + c$ have the exactly the same geometric properties but not the same fractional derivatives.

Some examples

The left fractional Riemann-Liouville derivative of a constant is not zero. Indeed, we have

$$D_+^\alpha[c] = \frac{c}{\Gamma(1-\alpha)}(t-a)^{-\alpha}, \quad (19)$$

for $\alpha \in]0, 1[$ and $t > a$. This properties in particular implies that a geometric interpretation of the fractional derivative is not possible. Indeed, from a geometrical view point, for an arbitrary constant $c \in \mathbb{R}$, the fonction f and $f + c$ have the exactly the same geometric properties but not the same fractional derivatives.

The left fractional Riemann-Liouville derivative of $f(t) = (t-a)^\beta$ is given by

$$D_+^\alpha[f](t) = \frac{\Gamma(\beta+1)}{\Gamma(\beta-\alpha+1)}(t-a)^{\beta-\alpha}, \quad (20)$$

for every $t \in [a, +\infty[$ if $\beta - \alpha \geq 0$ and for every $t \in]a, +\infty[$ if $-1 < \beta < 0$.

Left Caputo fractional derivative

$$\begin{aligned} {}_c D_+^\alpha[f] &= I_+^{1-\alpha} \left[\frac{df}{dt} \right], \\ {}_c D_-^\alpha[f] &= I_-^{1-\alpha} \left[\frac{df}{dt} \right], \end{aligned} \quad (21)$$

$${}_c D_\sigma^\alpha[c] = 0, \alpha \in]0, 1[, \sigma = \pm. \quad (22)$$

Connection between the RL and Caputo fractional derivative

Lemma

For every $\alpha \in]0, 1[$ and every $f \in AC([a, b], \mathbb{R}^d)$, $D_+^\alpha[f]$ and ${}_cD_+^\alpha[f]$ are defined almost everywhere on $[a, b]$ and

$$D_+^\alpha[f](t) = {}_cD_+^\alpha[f](t) + \frac{1}{\Gamma(1-\alpha)} \frac{f(a)}{(t-a)^\alpha}, \quad (23)$$

or more simply that

$${}_cD_+^\alpha[f] = D_+^\alpha[f - f(a)]. \quad (24)$$

Properties of fractional derivatives

► **Integration by part:**

$$\int_a^b f(t) D_\sigma^\alpha g(t) dt = \int_a^b D_{-\sigma}^\alpha f(t) g(t) dt, \quad \sigma = \pm. \quad (25)$$

► **Semi-group property:**

$$D_\sigma^\alpha D_\sigma^\beta = D_\sigma^{\alpha+\beta}, \quad 0 \leq \alpha, \beta \leq 1/2, \quad (26)$$

where we assume both functions $f, g \in AC^2([a, b])$.

In particular, when $\alpha = \beta = 1/2$, we have the specialization

$$D_-^{1/2} D_-^{1/2} = d/dt, \quad D_+^{1/2} D_+^{1/2} = -d/dt. \quad (27)$$

Interpreting fractional derivatives

Let T_t be a stochastic process with a probability density ρ_t . We assume that the Laplace transform \mathcal{L} of its probability density satisfies:

$$\mathcal{L}[\rho_t](s) = E_\alpha(-st^\alpha), \quad (28)$$

where $0 < \alpha < 1$ and E_α is the Mittag-Leffler function

$$E_\alpha(z) = \sum_{k \geq 0} \frac{z^k}{\Gamma(\alpha k + 1)}. \quad (29)$$

Interpreting fractional derivatives

Let T_t be a stochastic process with a probability density ρ_t . We assume that the Laplace transform \mathcal{L} of its probability density satisfies:

$$\mathcal{L}[\rho_t](s) = E_\alpha(-st^\alpha), \quad (28)$$

where $0 < \alpha < 1$ and E_α is the Mittag-Leffler function

$$E_\alpha(z) = \sum_{k \geq 0} \frac{z^k}{\Gamma(\alpha k + 1)}. \quad (29)$$

Let f be a sufficiently smooth function $f : t \rightarrow f(t)$, we denote by $f_\alpha(t)$ the quantity:

$$f_\alpha(t) = \mathbb{E}(f(T_t)) = \int_0^\infty \rho_t(\tau) f(\tau) d\tau, \quad (30)$$

where \mathbb{E} denotes the expectation.

Interpreting fractional derivatives

Let T_t be a stochastic process with a probability density ρ_t . We assume that the Laplace transform \mathcal{L} of its probability density satisfies:

$$\mathcal{L}[\rho_t](s) = E_\alpha(-st^\alpha), \quad (28)$$

where $0 < \alpha < 1$ and E_α is the Mittag-Leffler function

$$E_\alpha(z) = \sum_{k \geq 0} \frac{z^k}{\Gamma(\alpha k + 1)}. \quad (29)$$

Let f be a sufficiently smooth function $f : t \rightarrow f(t)$, we denote by $f_\alpha(t)$ the quantity:

$$f_\alpha(t) = \mathbb{E}(f(T_t)) = \int_0^\infty \rho_t(\tau) f(\tau) d\tau, \quad (30)$$

where \mathbb{E} denotes the expectation.

The main property of this new dynamical variable is that it satisfies :

Theorem

Let $f : \mathbb{R}^+ \rightarrow \mathbb{R}$ a sufficiently smooth function, then we have

$$\forall t \geq 0, \mathbb{E} \left(\frac{df}{dt}(T_t) \right) = {}_c D_-^\alpha (\mathbb{E}(f(T_t))), \quad (31)$$

where ${}_c D_-^\alpha$ is the fractional derivative of Caputo with inferior limit 0.

Fractionalization of PDEs

Theorem

Let $u : (t, x) \in \mathbb{R} \times \mathbb{R}^d \rightarrow u(t, x)$ be a solution of the following partial differential equation

$$\frac{\partial f}{\partial t}(t) + A(f(t)) = 0, \quad (32)$$

where A is an operator satisfying the transfer property

$$\mathbb{E}(A(f(T_t))) = A(\mathbb{E}(f(T_t))). \quad (33)$$

Then, the function

$$u_\alpha(t, x) = \mathbb{E}(u(T_t, x)), \quad (34)$$

satisfies the fractional partial differential equation

$${}_c\partial_{t,-}^\alpha u_\alpha(t, x) + A.(u_\alpha(t, x)) = 0. \quad (35)$$

where ${}_c\partial_{t,-}^\alpha u_\alpha$ is the Caputo derivative with respect to t of u_α .

Discrete variational derivative and integrals

For all $x \in \mathbb{R}$ and $n \in \mathbb{N}$, we denote by $x^{(n)}$ and $(x)_n$ the *Pochhammer symbols* defined by $x^{(0)} = (x)_0 = 1$ and for all $n \in \mathbb{N}^*$ by

$$x^{(n)} = x(x+1) \cdots (x+n-1), \quad (x)_n = x(x-1) \cdots (x-n+1). \quad (36)$$

Discrete variational derivative and integrals

For all $x \in \mathbb{R}$ and $n \in \mathbb{N}$, we denote by $x^{(n)}$ and $(x)_n$ the *Pochhammer symbols* defined by $x^{(0)} = (x)_0 = 1$ and for all $n \in \mathbb{N}^*$ by

$$x^{(n)} = x(x+1) \cdots (x+n-1), \quad (x)_n = x(x-1) \cdots (x-n+1). \quad (36)$$

Definition (Discrete fractional derivatives)

Let $0 < \alpha < 1$. The **right discrete fractional derivative of Grünwald-Letnikov** of superior limit b of order $\alpha > 0$ is the mapping from $C(, \mathbb{R}^d)$ to $C(+, \mathbb{R}^d)$ defined for all $f \in C(, \mathbb{R}^d)$ by

$$\Delta_+^\alpha[f](t_k) = \frac{1}{h^\alpha} \sum_{n=0}^{N-k} \frac{(-1)^n}{n!} (\alpha)_n f_{k+n}, \quad \forall k = 0, \dots, N-1. \quad (37)$$

The **left discrete fractional derivative of Grünwald-Letnikov** of inferior limit a of order $\alpha > 0$ is the mapping from $C(, \mathbb{R}^d)$ to $C(-, \mathbb{R}^d)$ defined for all $f \in C(, \mathbb{R}^d)$ by

$$\Delta_-^\alpha[f](t_k) = \frac{1}{h^\alpha} \sum_{n=0}^k \frac{(-1)^n}{n!} (\alpha)_n f_{k-n}, \quad \forall k = 1, \dots, N, \quad (38)$$

Discrete fractional integrals and properties

The previous formula keeps sense even for $\alpha < 0$. Following K. Diethelm ([?], §.2.4), we denote by $J_+^\alpha = \Delta_+^{-\alpha}$ and $J_-^\alpha = \Delta_-^{-\alpha}$ the right and left discrete fractional integrals.

Discrete fractional integrals and properties

The previous formula keeps sense even for $\alpha < 0$. Following K. Diethelm ([?], §.2.4), we denote by $J_+^\alpha = \Delta_+^{-\alpha}$ and $J_-^\alpha = \Delta_-^{-\alpha}$ the right and left discrete fractional integrals.

$$\Delta_-^\alpha[f] = \Delta_-^1 [J_-^{1-\alpha}[f]], \quad \Delta_+^\alpha[f] = \Delta_+^1 [J_+^{1-\alpha}[f]] \quad (39)$$

Discrete fractional integrals and properties

The previous formula keeps sense even for $\alpha < 0$. Following K. Diethelm ([?], §.2.4), we denote by $J_+^\alpha = \Delta_+^{-\alpha}$ and $J_-^\alpha = \Delta_-^{-\alpha}$ the right and left discrete fractional integrals.

$$\Delta_-^\alpha[f] = \Delta_-^1 [J_-^{1-\alpha}[f]], \quad \Delta_+^\alpha[f] = \Delta_+^1 [J_+^{1-\alpha}[f]] \quad (39)$$

Lemma (Semi-group property)

For all $\alpha, \beta > 0$, we have

$$\Delta_\sigma^\alpha [\Delta_\sigma^\beta] = \Delta_\sigma^{\alpha+\beta}, \quad J_\sigma^\alpha [J_\sigma^\beta] = J_\sigma^{\alpha+\beta}. \quad (40)$$

Moreover, we have

$$\Delta_\sigma^\alpha [J_\sigma^\alpha][f] = f \quad (41)$$

Variational structure for dissipative systems

- ▶ Dissipative systems do not possess a classical variational formulation. This follows from the Helmholtz's Theorem . A discussion was first provided by P.S. Bauer in 1931.

Variational structure for dissipative systems

- ▶ Dissipative systems do not possess a classical variational formulation. This follows from the Helmholtz's Theorem . A discussion was first provided by P.S. Bauer in 1931.
- ▶ Variational formulations can be obtained if one accepts to add to a given dissipative system a complementary set of equations as proved by H. Bateman in 1931. The main observation was that due to the irreversibility of a dissipative system, a given equation must be considered as physically incomplete as the dynamics is not invariant under time-reversing.

Another strategy ?

The Helmholtz theorem uses crucially the framework of the classical differential calculus and is no longer valid when one uses a different setting. The idea to use the **fractional calculus** as a possible framework to overcome this difficulty is originally due to F. Riewe in 1996.

Another strategy ?

The Helmholtz's theorem uses crucially the framework of the classical differential calculus and is no longer valid when one uses a different setting. The idea to use the **fractional calculus** as a possible framework to overcome this difficulty is originally due to F. Riewe in 1996.

Let L be a C^2 Lagrangian function $L : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$, $(x, v) \mapsto L(x, v)$, given $x, v \in \mathbb{R}^d$. The fractional action integral $L : C^2([a, b], \mathbb{R}^d) \rightarrow \mathbb{R}$ is defined by

$$L_\alpha(q) = \int_a^b L(q(t), D_-^\alpha q(t)) dt. \quad (42)$$

When $\alpha = 1$, we have $D_-^1 = D_+^1 = d/dt$ so that (42) reduces to the classical action functional.

Another strategy ?

The Helmholtz's theorem uses crucially the framework of the classical differential calculus and is no longer valid when one uses a different setting. The idea to use the **fractional calculus** as a possible framework to overcome this difficulty is originally due to F. Riewe in 1996.

Let L be a C^2 Lagrangian function $L : \mathbb{R}^d \times \mathbb{R}^d \mathbb{R}, (x, v) \mapsto L(x, v)$, given $x, v \in \mathbb{R}^d$. The fractional action integral $L : C^2([a, b], \mathbb{R}^d) \mathbb{R}$ is defined by

$$L_\alpha(q) = \int_a^b L(q(t), D_-^\alpha q(t)) dt. \quad (42)$$

When $\alpha = 1$, we have $D_-^1 = D_+^1 = d/dt$ so that (42) reduces to the classical action functional.

Extremals of L_α are solutions of a fractional differential system (see [?]) called the **fractional Euler-Lagrange equation** denoted by $(EL)_\alpha$ and given by

$$D_+^\alpha \frac{\partial L}{\partial v}(q, D_-^\alpha q) + \frac{\partial L}{\partial x}(q, D_-^\alpha q) = 0. \quad (43)$$

Another strategy ?

The Helmholtz's theorem uses crucially the framework of the classical differential calculus and is no longer valid when one uses a different setting. The idea to use the **fractional calculus** as a possible framework to overcome this difficulty is originally due to F. Riewe in 1996.

Let L be a C^2 Lagrangian function $L : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$, $(x, v) \mapsto L(x, v)$, given $x, v \in \mathbb{R}^d$. The fractional action integral $L : C^2([a, b], \mathbb{R}^d) \rightarrow \mathbb{R}$ is defined by

$$L_\alpha(q) = \int_a^b L(q(t), D_-^\alpha q(t)) dt. \quad (42)$$

When $\alpha = 1$, we have $D_-^1 = D_+^1 = d/dt$ so that (42) reduces to the classical action functional.

Extremals of L_α are solutions of a fractional differential system (see [?]) called the **fractional Euler-Lagrange equation** denoted by $(EL)_\alpha$ and given by

$$D_+^\alpha \frac{\partial L}{\partial v}(q, D_-^\alpha q) + \frac{\partial L}{\partial x}(q, D_-^\alpha q) = 0. \quad (43)$$

Problem: $D_-^{1/2} \circ D_+^{1/2} \neq d/dt$!

Restoring causality

H. Bateman idea: the classical set of variables used to describe a dissipative system has to be doubled in order to take into account the irreversibility of the dynamics. The new variable is understood as encoding the time reversed dynamics.

Restoring causality

H. Bateman idea: the classical set of variables used to describe a dissipative system has to be doubled in order to take into account the irreversibility of the dynamics. The new variable is understood as encoding the time reversed dynamics.

doubling state space coupled with the use of fractional derivatives proposed by J. Cresson and P. Inizan in 2010.

Restoring causality

H. Bateman idea: the classical set of variables used to describe a dissipative system has to be doubled in order to take into account the irreversibility of the dynamics. The new variable is understood as encoding the time reversed dynamics.

doubling state space coupled with the use of fractional derivatives proposed by J. Cresson and P. Inizan in 2010.

$$\mathbb{L}(x, y, v_x, v_y, w_x, w_y), \quad (44)$$

and fractional Lagrangian functionals of the form

$$L_{\alpha, \beta}(x, y) = \int_a^b \mathbb{L}(x, y, \dot{x}, \dot{y}, D_-^\alpha x, D_+^\beta y) dt. \quad (45)$$

Time reversal

$$x_*(x)(t) = x(a + b - t), \quad \forall t \in [a, b]. \quad (46)$$

Lemma (Time reversal duality)

Let $x \in AC([a, b])$, the following diagram commutes

$$\begin{array}{ccc} x & \xrightarrow{D_-^\alpha} & D_-^\alpha[x] \\ \downarrow *_{a,b} & & \downarrow *_{a,b} \\ x_* & \xrightarrow{D_+^\alpha} & D_+^\alpha[x_*] \end{array}, \quad (47)$$

which implies the equality

$$D_+^\alpha[x_*] = (D_-^\alpha[x])_* \quad (48)$$

Constraining the extended Lagrangian

- ▶ The dissipative term must be connected with the emergence of a fractional term in the Lagrangian.

Constraining the extended Lagrangian

- ▶ The dissipative term must be connected with the emergence of a fractional term in the Lagrangian.
- ▶ For a reversible dynamical system, the two equations must be the same under time reversal.

Constraining the extended Lagrangian

- ▶ The dissipative term must be connected with the emergence of a fractional term in the Lagrangian.
- ▶ For a reversible dynamical system, the two equations must be the same under time reversal.

$$\mathbb{L}(x, x_*, v, v_*, w, w_*) = L(x, v) + L(x_*, v_*) + P(w, w_*), \quad (49)$$

Constraining the extended Lagrangian

- ▶ The dissipative term must be connected with the emergence of a fractional term in the Lagrangian.
- ▶ For a reversible dynamical system, the two equations must be the same under time reversal.

$$\mathbb{L}(x, x_*, v, v_*, w, w_*) = L(x, v) + L(x_*, v_*) + P(w, w_*), \quad (49)$$

- ▶ The dynamics of x (resp. x_*) depends only on x (resp. x_*) and derivatives of the form $D_-^\gamma x$ (resp. $D_+^\gamma x_*$).
- ▶ The dynamics satisfied by x_* is the time reversed dynamics of x .

Restriction on variations ?

Considering reversible variation, i.e. such that

$$h = h_*$$
 (50)

and the previous constraints, we have

$$\mathbb{L}(x, x_*, v, v_*, w, w_*) = L(x, v) + L(x_*, v_*) + \gamma w w_*,$$
 (51)

If

$$\frac{d}{dt} \left(\frac{\partial L}{\partial v}(x, \dot{x}) \right) - \frac{\partial L}{\partial x}(x, \dot{x}) + \gamma D_-^{\alpha+\beta} x = 0.$$
 (52)

then (x, x_*) is a critical point of \mathbb{L} !