

# Use of polar invariants for uncertainty quantification and optimization of the aeroelastic response of composite structures

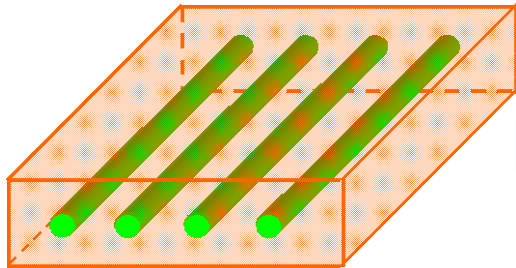
**Angela Vincenti**

Institut d'Alembert, Sorbonne Université

GDR-GDM, Jussieu, 23 Novembre 2023

# Optimization of composite materials and structures

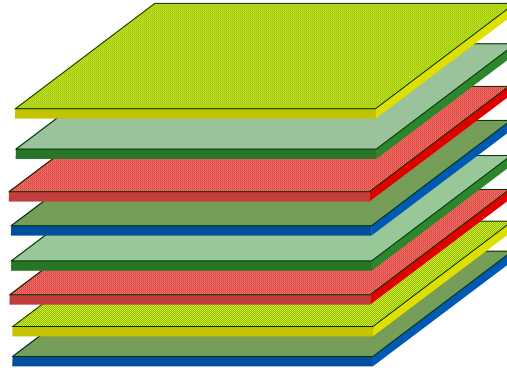
## MICROSCALE



Orthotropic lamina  
(fibers + matrix)



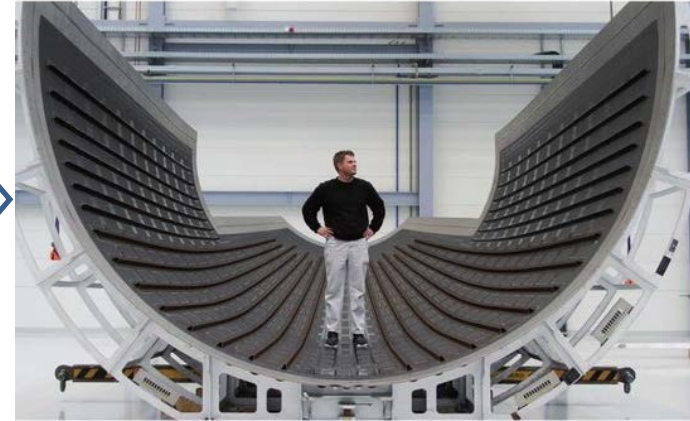
## MESOSCALE



Laminated plate



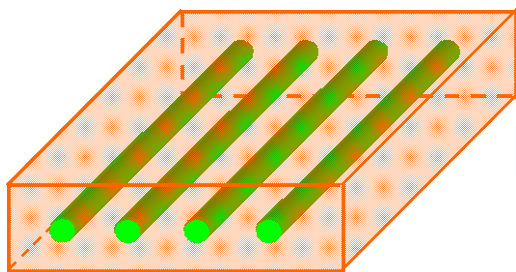
## MACROSCALE



Complex composite structures  
Airbus 350 [Hilken, SAE Int J Aerosp 2017]

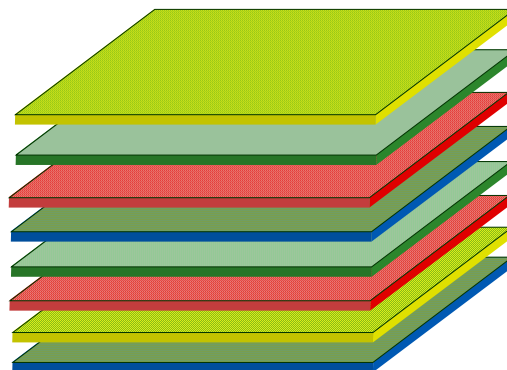
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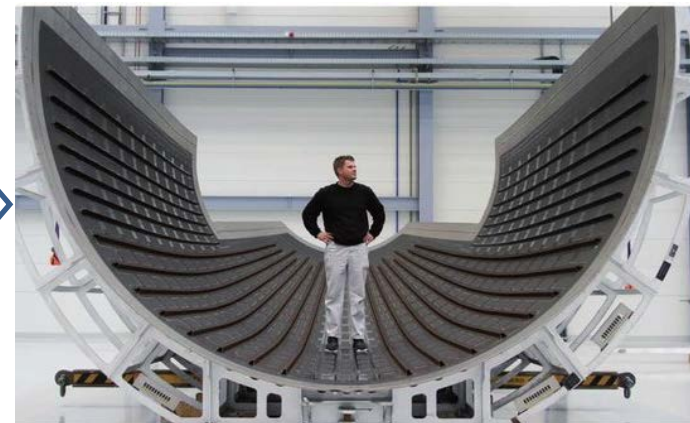
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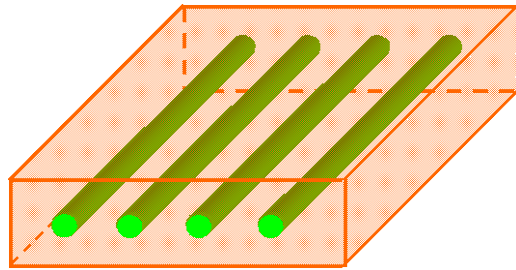
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## Interesting features of composite materials :

- Large strength- and stiffness-to-weight ratio
- Heterogeneity generally hinders fracture propagation
- **Multiple combinations of reinforcement architecture : free design scheme**

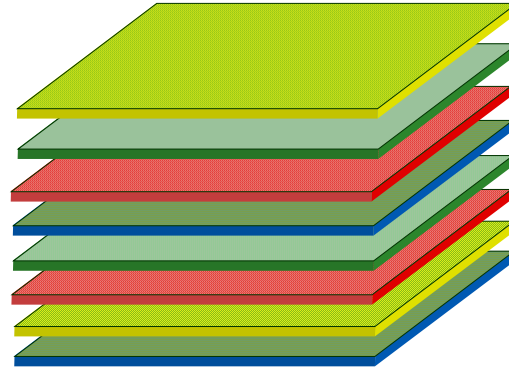
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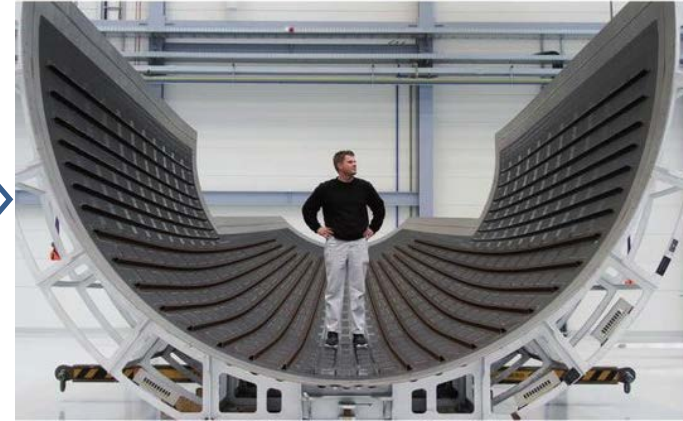
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## Applications to lightweight structures



HALE Helios  
(NASA, 2004)

Boeing 787 Dreamliner



■ Carbon laminate  
■ Carbon sandwich  
■ Other composites  
■ Aluminum  
■ Titanium



ESA's Ariane 6

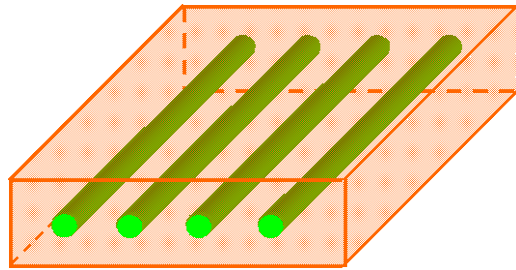
Substance  
class C catamaran  
(ETS Montréal)





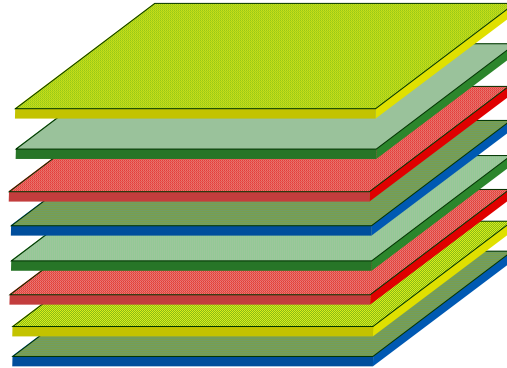
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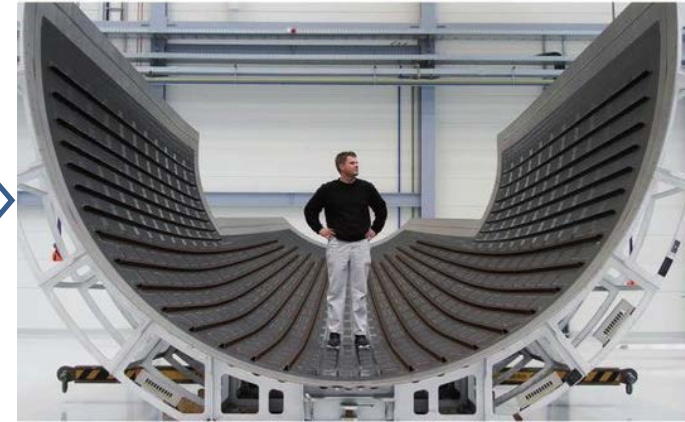
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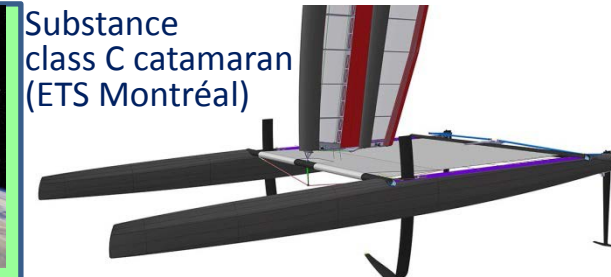


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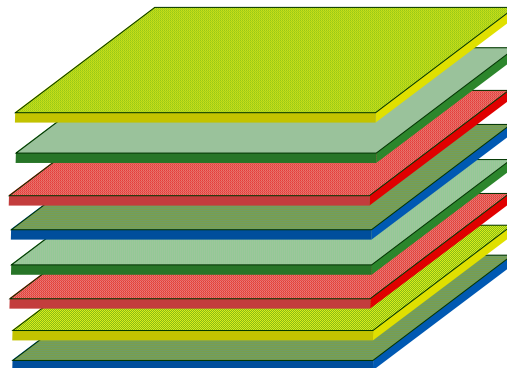


Orthotropic lamina

$E_1, E_2, G_{12}, \nu_{12}$



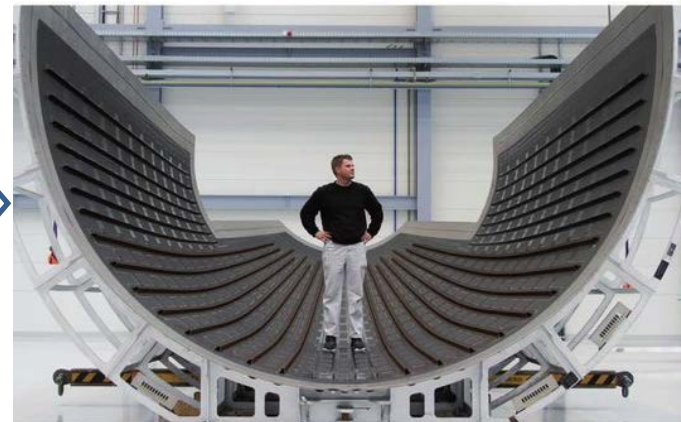
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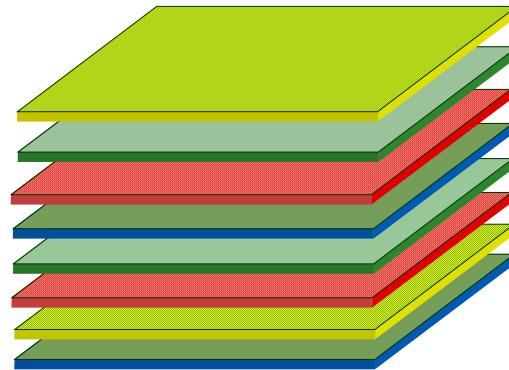


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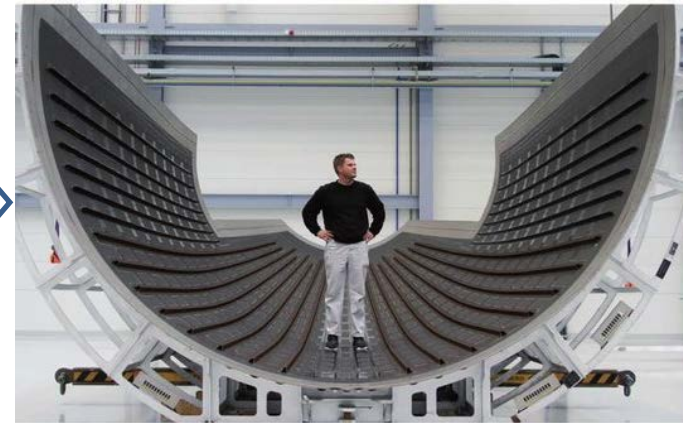
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[Hilken, SAE Int J Aerospace, 2017]

## Scientific challenges :

- Assembly of layers oriented at angles  $\delta_k$  ( $k = 1, \dots, N$ ) : **high number of variables**
- **Complex behaviour** : anisotropy, different in-plane and out-of-plane response, **couplings** (elastic, thermo-elastic, etc.)
- Highly **non-linear and non-convex relations** in terms of orientation angles  $\delta_k$

# Optimization of composite materials and structures

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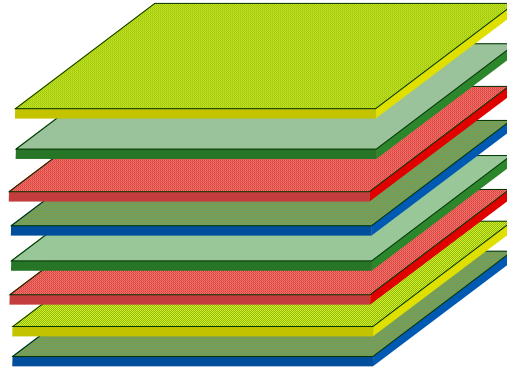


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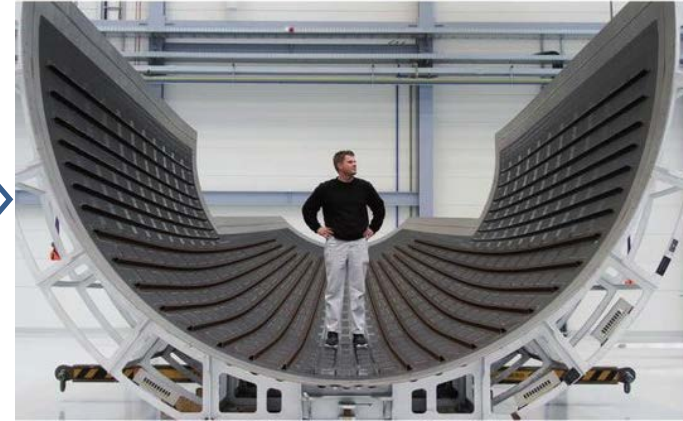
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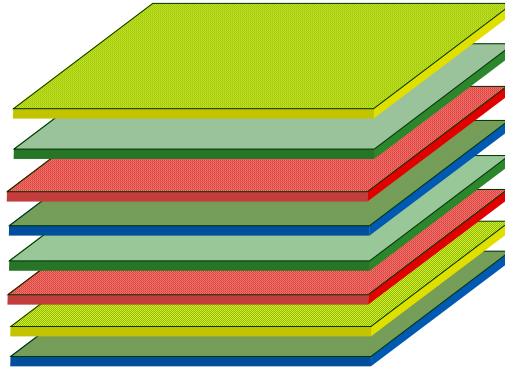


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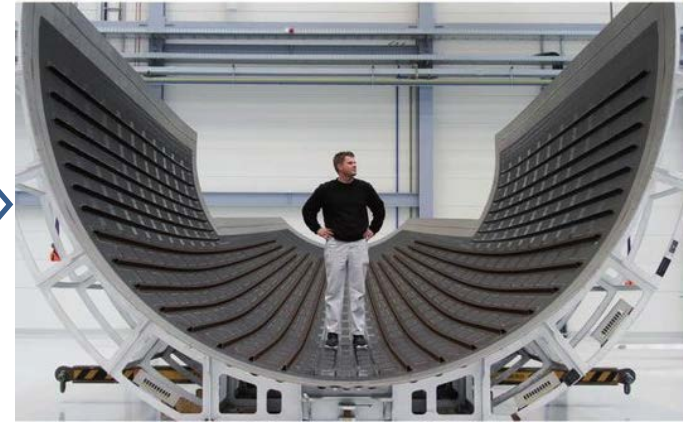
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**Complex composite structures**

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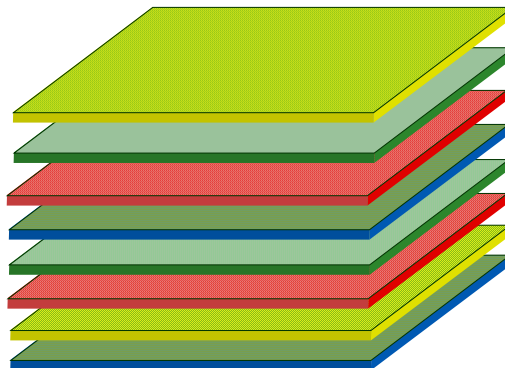


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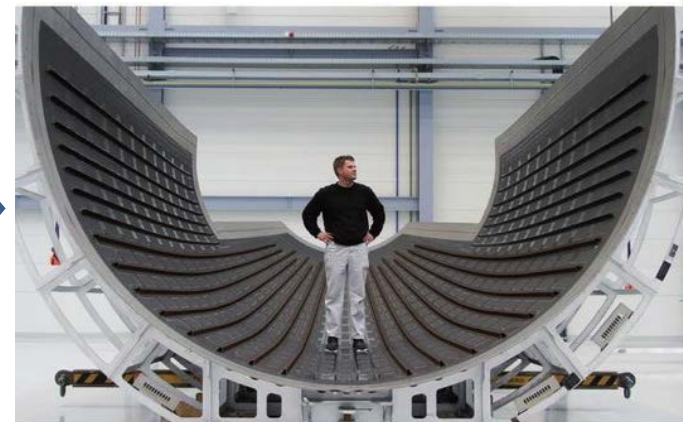
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- The **number of constitutive modules** can itself be a **design variable**
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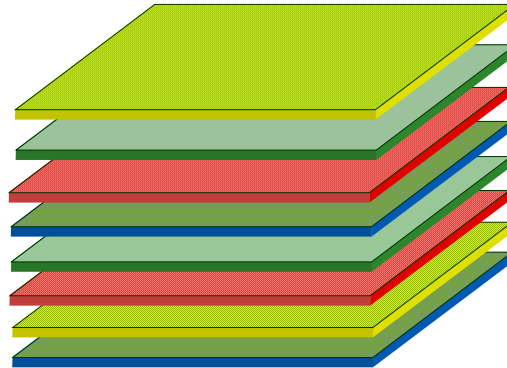


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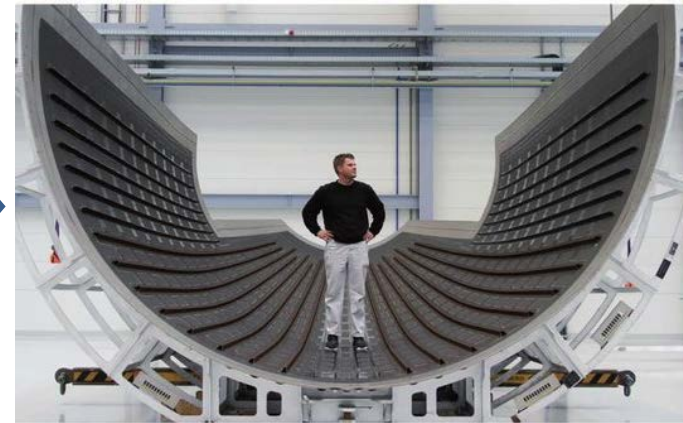
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## 2. Optimization of variable-stiffness composite structures

# Optimal design of composite structures via invariants

## 1. Optimization of composite laminated plates

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# The polar representation of plane tensors

**Second-order symmetric tensors** : strain  $\boldsymbol{\varepsilon}$ , stress  $\boldsymbol{\sigma}$ , forces and moments  $\mathbf{N}$  and  $\mathbf{M}$ , etc.

$$L_{11} = T + R \cos 2\Phi$$

$$L_{12} = R \sin 2\Phi$$

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**Fourth-order symmetric tensors** : stiffness  $\mathbf{Q}$ , compliance  $\mathbf{S}$ , laminate's tensors  $\mathbf{A}$ ,  $\mathbf{a}$ , etc.

$$Q_{11} = T_0 + 2T_1 + R_0 \cos 4\Phi_0 + 4R_1 \cos 2\Phi_1$$

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**Polar angles**  $\Phi_0$  and  $\Phi_1$

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(Verchery, *EuroMech* 1979; Vannucci, *Meccanica* 2005)

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**Invariants  $T$  and  $R$**   $\longrightarrow$  Spherical and deviatoric

**Polar angle  $\Phi$**   $\longrightarrow$  First principal axis

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**Invariants**  $T_0$  and  $T_1$   $\longrightarrow$  Isotropic components  
 $R_0$  and  $R_1$   $\longrightarrow$  Anisotropic components (moduli)  
 $\Phi_0 - \Phi_1$   
**Polar angles**  $\Phi_0$  and  $\Phi_1$   $\longrightarrow$  Anisotropic phase angles

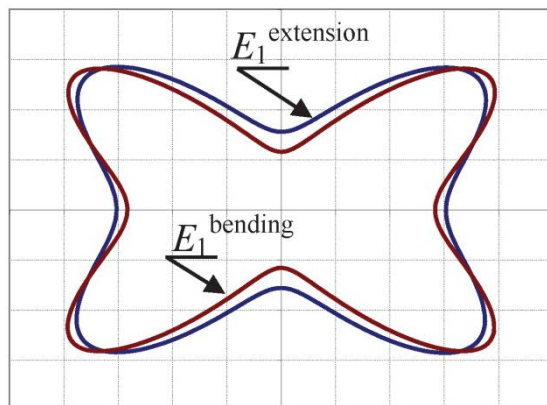
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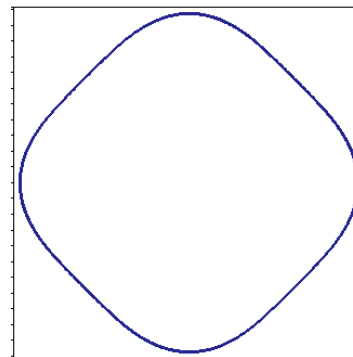
# Polar conditions for 2D elastic symmetries

Elastic symmetry	Polar condition	Remaining polar parameters	Principal axis
Orthotropy	$\Phi_0 - \Phi_1 = K \frac{\pi}{4}, K = 0, 1$	$T_0, T_1, R_K = (-1)^K R_0, R_1$	$\Phi_1$
$R_0$ -orthotropy	$R_0 = 0$	$T_0, T_1, R_1$	$\Phi_1$
Square symmetry	$R_1 = 0$	$T_0, T_1, R_0$	$\Phi_0$
Isotropy	$R_0 = R_1 = 0$	$T_0, T_1$	none

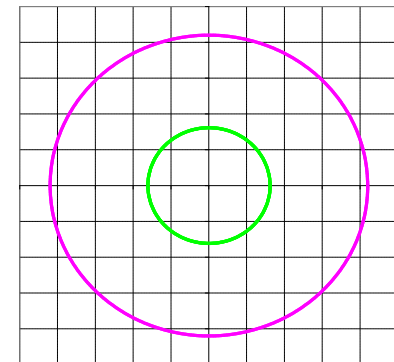
## Orthotropy



## Square symmetry



## Isotropy



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## Main advantages of the polar representation :

- Polar invariants are **intrinsic tensor's descriptors**
- **Simple transformation** of polar angles
- **Physical interpretation** of polar components
- **Explicit conditions for elastic symmetries** on polar invariants
- **Reduction of the number of polars parameters** for symmetric tensors
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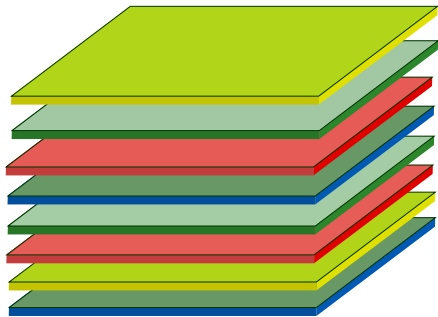
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 **Polar representation of the behaviour of composite laminated plates**

(Verchery, *EuroMech* 1979; Vannucci, *Meccanica* 2005)

# Polar representation of the Classical Laminated Plate Theory



$$\begin{Bmatrix} \mathbf{N} \\ \mathbf{M} \end{Bmatrix} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{bmatrix} \begin{Bmatrix} \boldsymbol{\varepsilon} \\ \boldsymbol{\chi} \end{Bmatrix}$$

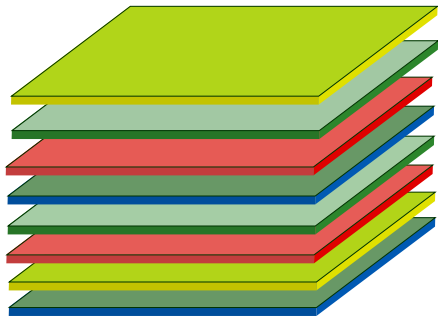
The **CLPT** expresses the **homogenised behaviour of a laminated plate** ( $n$  layers, stacking sequence  $[\delta_k]$ ; general case of a **hybrid laminate**):

$$\mathbf{A} = \sum_{k=1}^n \mathbf{Q}_k(\delta_k) (z_k - z_{k-1})$$

$$\mathbf{B} = \frac{1}{2} \sum_{k=1}^n \mathbf{Q}_k(\delta_k) (z_k^2 - z_{k-1}^2)$$

$$\mathbf{D} = \frac{1}{3} \sum_{k=1}^n \mathbf{Q}_k(\delta_k) (z_k^3 - z_{k-1}^3)$$

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## The polar expressions of the Classical Laminated Plate Theory

( $n$  layers, stacking sequence  $[\delta_k]$  ; general case of a **hybrid laminate**) :

$$T_0^A, T_0^B, T_0^D = \frac{1}{m} \sum_{k=1}^n T_{0k} (z_k^m - z_{k-1}^m)$$

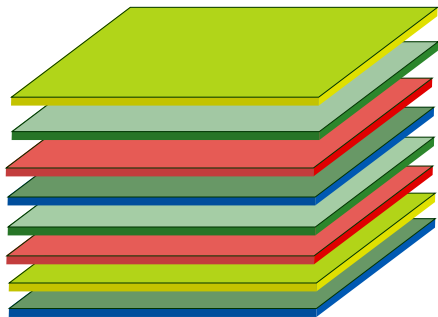
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# Polar representation of the Classical Laminated Plate Theory



$$\begin{Bmatrix} \mathbf{N} \\ \mathbf{M} \end{Bmatrix} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{bmatrix} \begin{Bmatrix} \boldsymbol{\varepsilon} \\ \boldsymbol{\chi} \end{Bmatrix}$$

The polar expressions of the Classical Laminated Plate Theory

(common case of identical layers,  $n$  layers, stacking sequence  $[\delta_k]$ ):

**Isotropic polar components :**  $T_0^A = hT_0$  ,  $T_0^B = 0$  ,  $T_0^D = \frac{h^3}{12}T_0$

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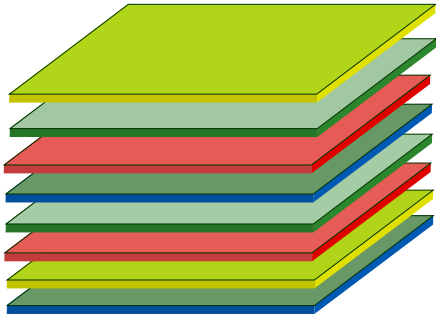
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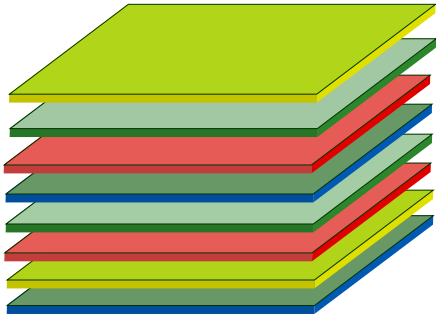
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*lamination parameters*

(Tsai & Pagano, 1968 ; Tsai, 1980)

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**Remark :** *lamination parameters* are issued from the CLPT (stiffness response, laminates made of identical layers) whilst the **polar representation is more general**

# Polar invariants and optimal design of composite laminates

## 1. Optimization of composite laminated plates

- i. A unified formulation for the optimization of composite laminated plates  
(Vincenti et al, *JOGO* 2010 ; Vincenti et al, *MAMS* 2012)
- ii. Extension to multi-physical couplings (thermo-elastic, piezo-elastic, ...)  
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**"Class 0"** formulation : **design** of laminates w.r.t. **elastic symmetries**

**"Class 1"** formulation : **design of elastic symmetries with constraints**  
on mechanical properties

**"Class 2"** formulation : **optimization of laminates**  
**including conditions on elastic symmetries**

PhD thesis of R. Ahmadian

Collaboration with P. Vannucci (Université de Versailles)

# "Class 0" : elastic symmetries of laminates

## Context :

- **Empirical rules for elastic symmetries** (symmetric stacking sequences, angle-ply, cross-ply) : **restriction of the design space** and **sub-optimal solutions**  
(Liu et al, *CMAME* 2000 ; Soremekun et al, *Comput & Struct* 2001 ; Herencia et al, *AIAA J* 2007 ; ... )
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## The design of elastic symmetries as an identification problem :

(P) Find  $\delta \in \Delta_{\text{adm}}$  such that :  $\min_{\delta} I(\mathbf{P}(\delta))$

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# Examples of "Class 0" problem : unconstrained optimization

**1. Uncoupled orthotropic laminate with coincident axes in membrane and bending plus thermoelastic symmetries (direction of zero expansion):**

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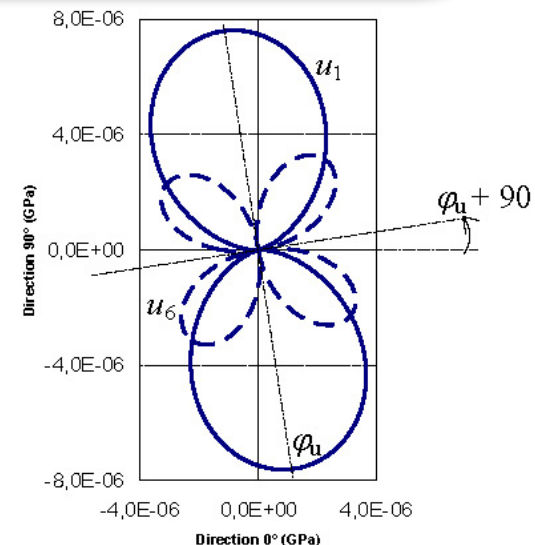
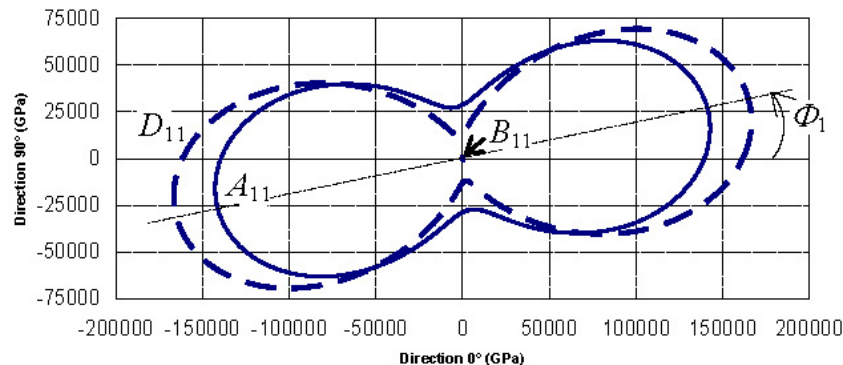
where :

- $I(\mathbf{P}(\delta))$  expresses the combination of objectives on elastic and thermo-elastic symmetries
- $\Delta_{\text{adm}}$  : continuous orientations, from  $-90^\circ$  to  $90^\circ$

**Study case : 12-ply laminate**

**Solution :**

[0/23.0/11.3/11.2/...  
-33.7/ 85.8/30.9/...  
-13.4/ -0.1/22.1/...  
21.6/ -0.9]



# Examples of "Class 0" problem : unconstrained optimization

## 2. Uncoupled quasi-homogeneous square-symmetric laminate plus thermoelastic symmetries (isotropic thermal expansion):

(P) Find  $\delta \in \Delta_{\text{adm}}$  such that :  $\min_{\delta} I(\mathbf{P}(\delta))$

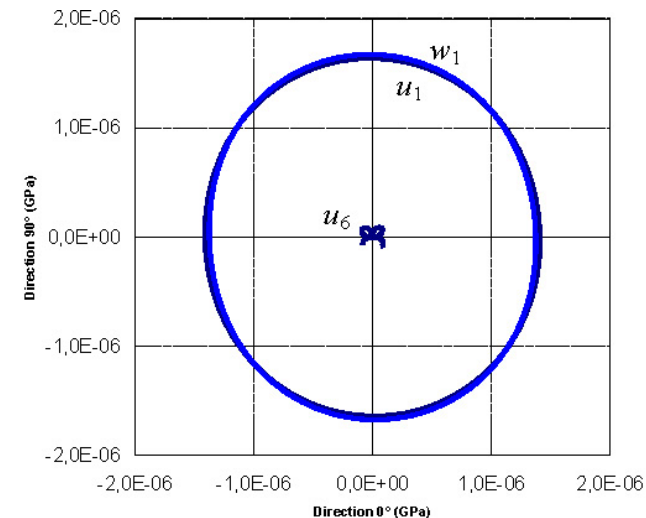
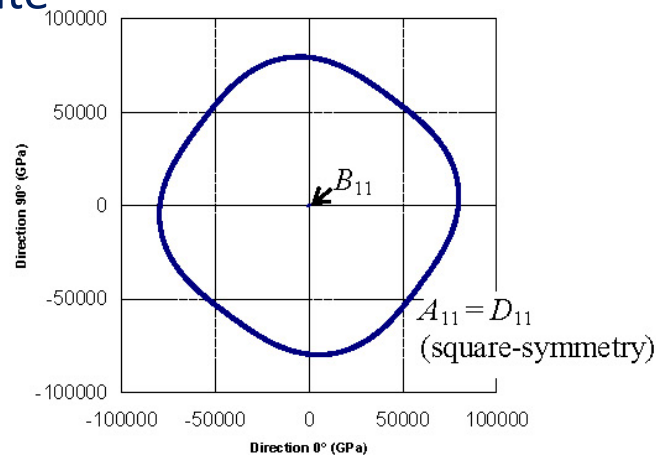
where :

- $I(\mathbf{P}(\delta))$  expresses the combination of objectives on elastic and thermo-elastic symmetries
- $\Delta_{\text{adm}}$  : discrete set of orientations, from  $-90^\circ$  to  $90^\circ$ , step  $5^\circ$

Study case : 24-ply laminate

Solution :

[0/25/-45/-85/-85/75/...  
-30/40/45/90/-15/-75/...  
20/-45/0/30/10/-70/...  
75/-20/-85/-5/-65/50]



# "Class 2" : optimization of laminates with elastic symmetries

## Optimization of laminates with elastic symmetries :

(P) Find  $(\boldsymbol{\delta}, \mathbf{x})$  such that :

$$\min_{\boldsymbol{\delta}, \mathbf{x}} f(\boldsymbol{\delta}, \mathbf{x})$$

subject to :

$$\left\{ \begin{array}{l} g_i(\boldsymbol{\delta}, \mathbf{x}) \leq 0 \quad i = 1, \dots, r, \\ h_j(\boldsymbol{\delta}, \mathbf{x}) = 0 \quad j = 1, \dots, m, \\ I(\mathbf{P}(\boldsymbol{\delta})) < \epsilon \\ \mathbf{x}_L \leq \mathbf{x} \leq \mathbf{x}_U, \\ \boldsymbol{\delta} \in \Delta_{\text{adm}} \end{array} \right.$$

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- ✓ Elastic symmetries among design constraints
- ✓ Variables can be layers' angles  $\boldsymbol{\delta}$ , but also other parameters  $\mathbf{x}$  (e.g. geometry)
- ✓ As for "Class 0/1" problems, functions are **highly non linear and non convex**
- ✓ Optimization of simple laminated structures



# Example of "Class 2" problem : constrained optimization

**Max buckling load with uncoupling, in-plane and bending orthotropy with coincident axis, constraints on Young's moduli:**

(P) Find  $(\delta)$  such that :

$$\max_{\delta} \left( \min_{m,n} \lambda_{\text{crit}}(\delta) \right)$$

subject to :

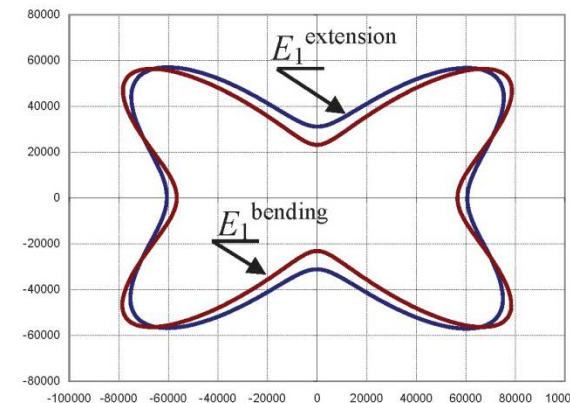
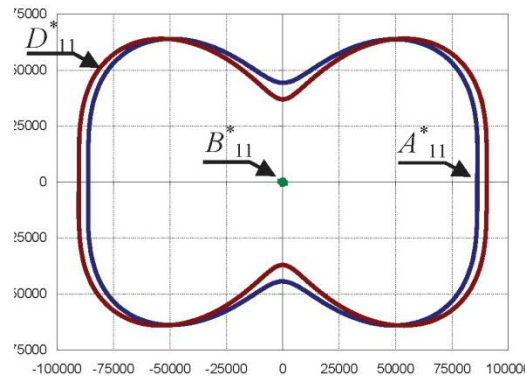
$$\begin{cases} I(\mathbf{P}(\delta)) < \epsilon \\ E_x^A(\delta) \geq 60\text{GPa} , \\ E_y^A(\delta) \geq 30\text{GPa} , \\ \delta \in \Delta = \{-89, -88, \dots, 90\} \end{cases}$$

(Vincenti et al:  
JOGO 2010 ; MAMS 2012)

**Study case :** 16-ply simply-supported rectangular plate under bi-axial compression

**Solution :**

[-24/39/-47/37/32/-47/-6/-47/  
/55/59/18/-38/-38/19/-40/42]



# Optimal design of laminates using the polar formalism

## 1. Optimization of composite laminated plates (Vincenti & Vannucci, *ECCM* 2006 ; Vannucci & Vincenti, *Compos Struct* 2007 ; Vincenti et al, *JOGO* 2010 ; Vincenti et al., *MAMS* 2012)

### Final remarks :

- ✓ Design of elastic symmetries formulated as an **unconstrained optimization** problem or as a **constraint** of a structural optimization problem
- ✓ Control of **multi-physical couplings** (thermo-, hygro- or piezo-elastic stability) as an **unconstrained optimization** problem
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**How to tackle optimization of complex composite structures ?**  
**Two-level approach based on the polar formalism**



# Two-level approach : separating the macro- and meso-scale

**Step 1 (macro-) : structural optimization**

$$\min_{\mathbf{A}, \mathbf{B}, \mathbf{D}, \mathbf{x}} f(\mathbf{A}, \mathbf{B}, \mathbf{D}, \mathbf{x})$$

subject to :

$$\begin{cases} g_i(\mathbf{A}, \mathbf{B}, \mathbf{D}, \mathbf{x}) \leq 0 & (i = 1, \dots, r) \\ h_j(\mathbf{A}, \mathbf{B}, \mathbf{D}, \mathbf{x}) = 0 & (j = 1, \dots, m) \\ \mathbf{x}_L \leq \mathbf{x} \leq \mathbf{x}_U \\ \mathbf{A}, \mathbf{B}, \mathbf{D} \in \mathcal{D}_{\text{adm}} \end{cases}$$

**Step 2 (meso-) : search of optimal stacks**

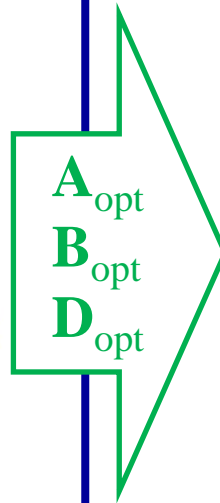
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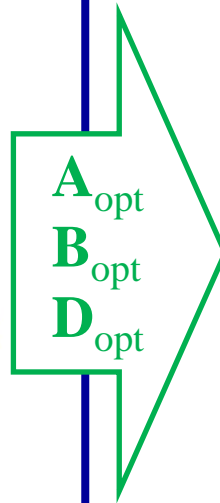
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**Use of the polar formalism**



# Polar representation of an orthotropic laminate

- **Uncoupled laminates** ( $\mathbf{B} = \mathbf{O}$ ) : remaining tensors  $\mathbf{A}$  and  $\mathbf{D}$  (in-plane and bending)
- **Laminates made of identical layers** : isotropic components  $T_0$  and  $T_1$  are fixed
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- **Orthotropy** : two polar invariants  $R_K = (-1)^K R_0$  and  $R_1$ , plus one polar angle  $\Phi_1$

## Thermodynamic conditions :

$$T_0 - R_K > 0$$

$$T_1 (T_0 + R_K) - 2R_1^2 > 0$$

[Vincenti & Desmorat, *JElas* 2010]

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[Vincenti & Desmorat, *JElas* 2010]

## Geometric bounds :

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[Vannucci, *JElas* 2012]



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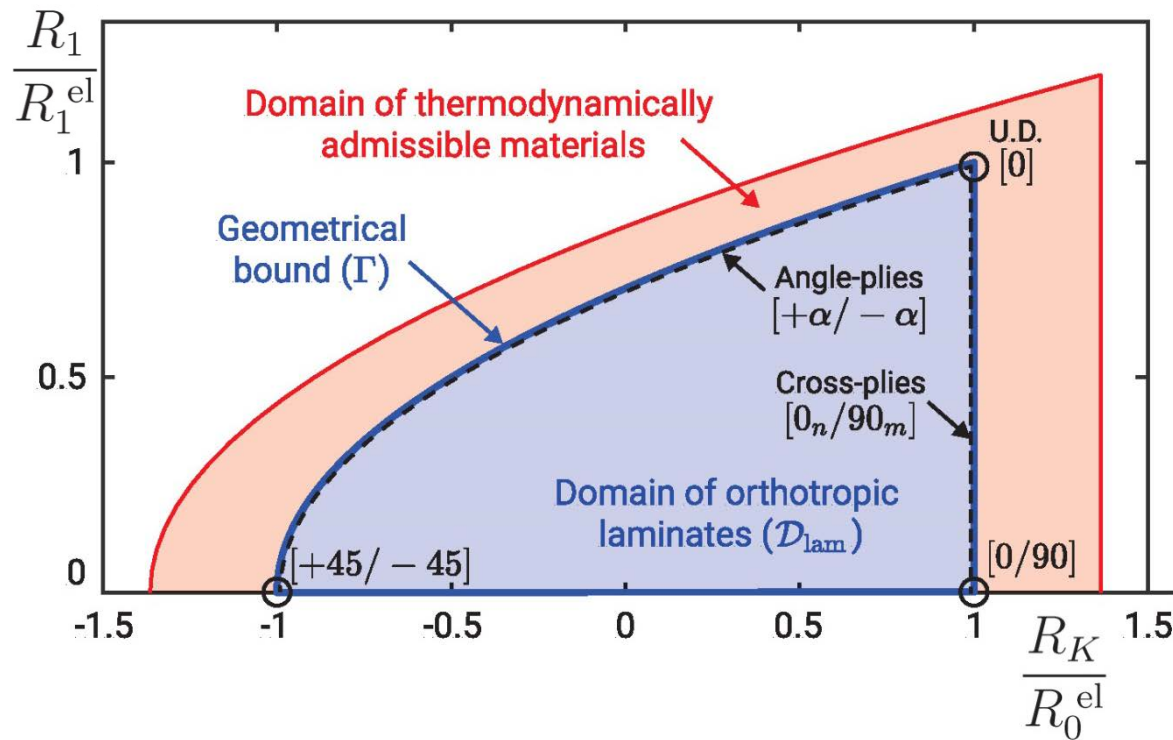
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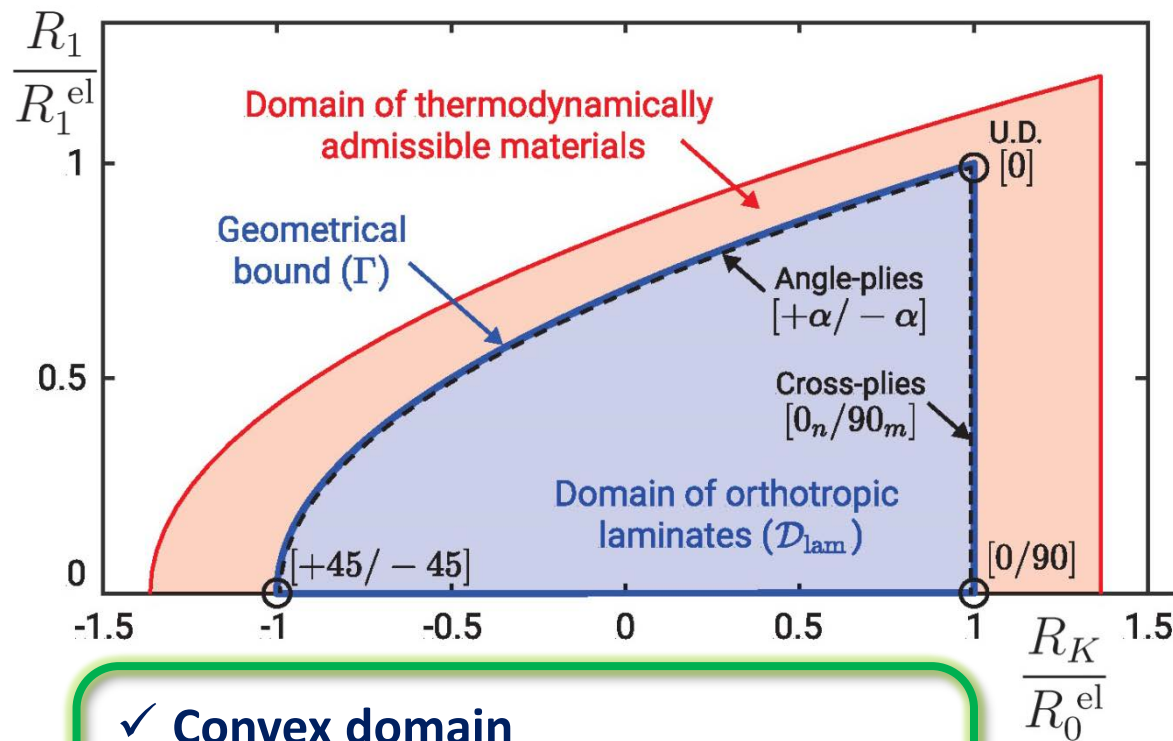
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[Vannucci, *JElas* 2012]



- ✓ **Convex domain**
- ✓ **All feasible orthotropic laminates**
- ✓ **All elastic symmetries are included**

# Polar formulation of the two-level approach

## Step 1 (macro-) : structural optimization

$$\min_{R_K, R_1, \Phi_1, \mathbf{x}} f(R_K, R_1, \Phi_1, \mathbf{x})$$

subject to :

$$\left\{ \begin{array}{l} g_i(R_K, R_1, \Phi_1, \mathbf{x}) \leq 0 \quad (i = 1, \dots, r) \\ h_j(R_K, R_1, \Phi_1, \mathbf{x}) = 0 \quad (j = 1, \dots, m) \\ \mathbf{x}_L \leq \mathbf{x} \leq \mathbf{x}_U \\ R_K - R_0^{\text{el}} \leq 0 \\ 2 \left( \frac{R_1}{R_1^{\text{el}}} \right)^2 - \frac{R_K}{R_0^{\text{el}}} - 1 \leq 0 \end{array} \right.$$

(C. Julien, *PhD thesis* 2010 ; Jibawy et al, *IJSS* 2011 ; Montemurro et al, *JOTA* 2012 ; Montemurro, *PhD thesis* 2012)

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$$\begin{array}{c} R_K^{\text{opt}} \\ R_1^{\text{opt}} \\ \Phi_1^{\text{opt}} \end{array}$$

## Step 2 (meso-) : search of optimal stacks

Find the stacking sequence  $\delta$  such that the laminate is :

- uncoupled
- orthotropic  
(or other elastic symmetry)

and :

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Solve the **identification problem** :

$$\min_{\delta} F(\delta)$$

(C. Julien, *PhD thesis* 2010 ; Jibawy et al, *IJSS* 2011 ; Montemurro et al, *JOTA* 2012 ; Montemurro, *PhD thesis* 2012)

# Optimization of composite structures via the polar formalism

2. Optimization of variable-stiffness composite structures using a two-level method based on the polar formalism
  - i. Compliance minimisation of tow-steered composite structures
  - ii. Optimization of modular composite structures

Final remarks and open questions :

- Formulation of optimization problems : how to take into account conditions depending on the stacking sequence, such as strength, delamination, ...?  
How to express the correlation between **A** and **D** ?



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**Influence of anisotropy on non-linearities and instabilities**

# Aeroelastic response of composite structures : optim & UQ

1. Optimization of composite laminated plates
2. Optimization of variable-stiffness composite structures
3. Influence of anisotropy and uncertainties on non-linearities and instabilities
  - i. **Design of multistable composite shells**  
(Hamouche et al : *Meccanica* 2016, *PRSA* 2016 ; Brunetti et al : *IJSS* 2016, *Compos Struct* 2018)  
Collaboration with C. Maurini (d'Alembert) and S. Vidoli (Univ Roma La Sapienza)  
ANR project JC SLENDER 2014-18
  - ii. **Aeroelastic optimization of composite plate wings**
  - iii. **Influence of uncertainties on the aeroelastic response of composite plate wings**  
(Nitschke et al, *Compos Struct* 2019)  
PhD theses of C. Nitschke (2014-18) and M. Sharifi (2019-2023)  
Collaboration with J-C. Chassaing (d'Alembert)

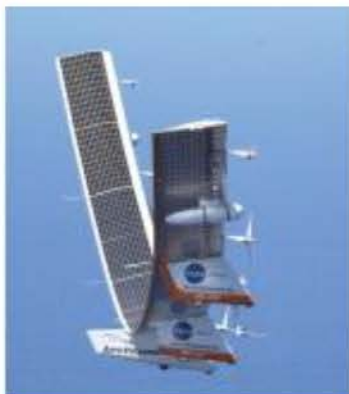
# Aeroelastic response of composite plate wings

- **Fluid-Structure Coupling** : interaction of elastic, inertial and aerodynamic forces
- **Coupled equations of motion** :

$$[\mathbf{M}]\ddot{\mathbf{w}} + [\mathbf{C}]\dot{\mathbf{w}} + [\mathbf{K}]\mathbf{w} = F_{aero}(\mathbf{w}, \dot{\mathbf{w}}, \ddot{\mathbf{w}})$$

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## Crash of the Helios drone due to aeroelastic flutter in 2004



[NOLL et al : Investigation of the Helios prototype aircraft mishap. NASA Report, 9, 2004]

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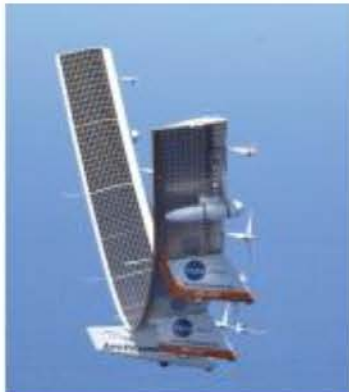
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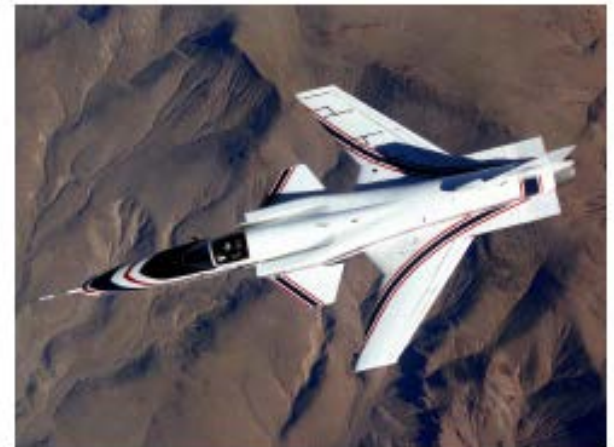
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- **Aeroelastic tailoring of composite wings** : **maximisation** of the **aeroelastic performances** (critical velocity, flutter margin) wrt **anisotropic elastic properties**
- **Limited to small number of plies** and/or **symmetric stacking sequences**

(Weissnar, *J Aircraft* 1981 ; Kameyama, *Comput & Struct* 2007 ;  
Thuwis et al, *SMDO* 2010 ; Stodieck et al, *AIAA J* 2015)



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# Aeroelastic optimization via the polar formalism

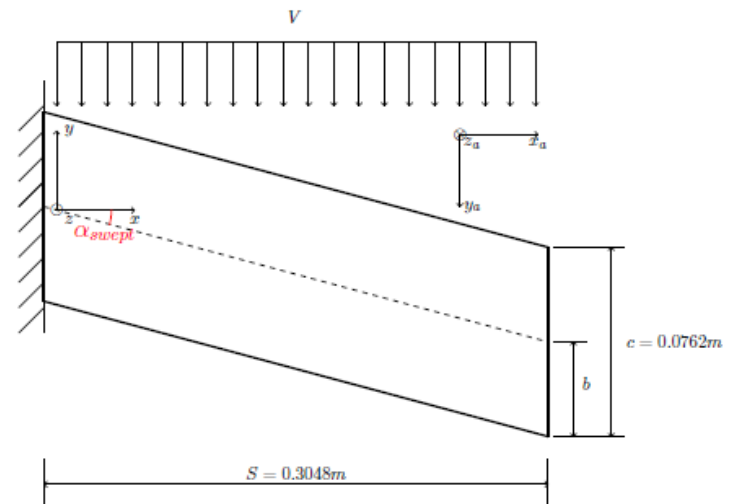
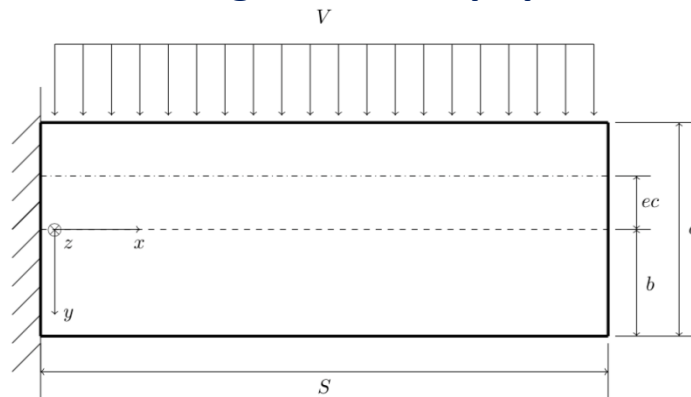
## Two-level polar approach for aeroelastic analysis of composite plate wings

- i. Aeroelastic deterministic optimization
- ii. Influence of uncertainties on the aeroelastic response
- iii. Aeroelastic optimization in a stochastic framework (robust, RBDO)

### Cases of study

- ✓ Plate wing made of a **16-ply orthotropic laminate** : polar formalism ( $R_K$ ,  $R_1$  and  $\Phi_1$ )
- ✓ Structural model : FE orthotropic plate approximation (*Fenics*)
- ✓ Aerodynamic model : Doublet Lattice Method (Albano & Rodden, *AIAA J* 1969)
- ✓ Aeroelastic solver : modal analysis via the p-k method (Hassig, *J of Aircraft* 1971)

### Models of straight and swept plate wings



# Aeroelastic analysis of a plate composite wing

By coupling the FE model of the plate and the DLM approximation :

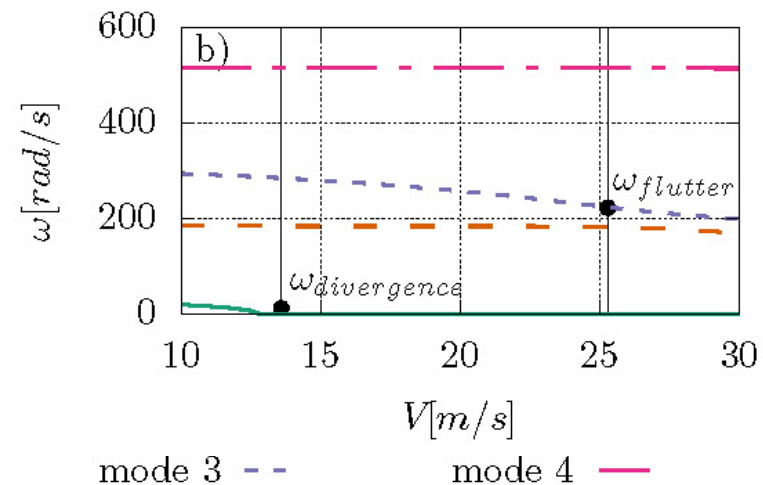
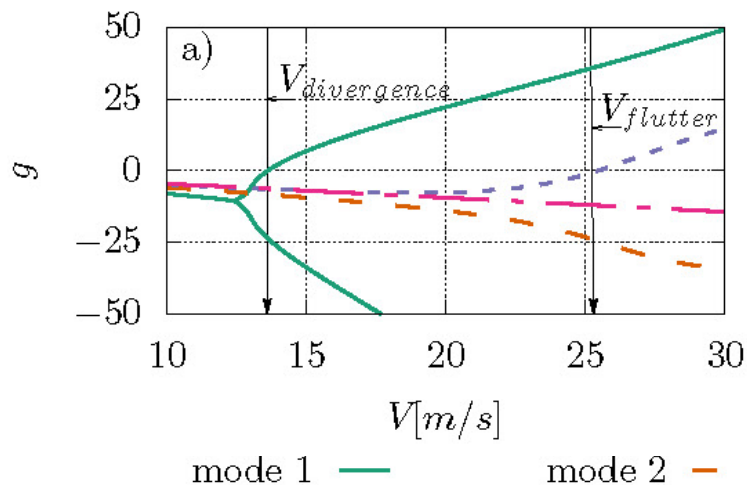
$$\hat{\mathbf{M}}\ddot{\mathbf{q}} - \omega \mathbf{A}_{aero}^I \dot{\mathbf{q}} + (\hat{\mathbf{K}} - \omega^2 \mathbf{A}_{aero}^R) \mathbf{q} = 0$$

which can be transformed into a **1st-order eigenvalue problem** :

$$\begin{bmatrix} \mathbf{I} & 0 \\ 0 & \hat{\mathbf{M}} \end{bmatrix} \begin{Bmatrix} \dot{\mathbf{q}} \\ \ddot{\mathbf{q}} \end{Bmatrix} - \begin{bmatrix} 0 & \mathbf{I} \\ -(\hat{\mathbf{K}} - \omega^2 \mathbf{A}_{aero}^R) & \omega \mathbf{A}_{aero}^I \end{bmatrix} \begin{Bmatrix} \mathbf{q} \\ \dot{\mathbf{q}} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

and the solved by the use of the **p-k method**.

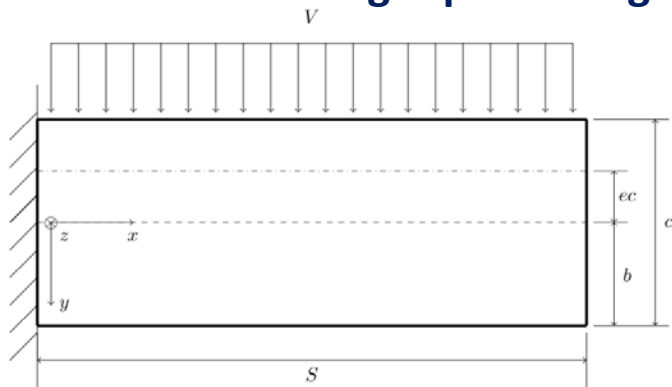
**Example** : stacking sequence  $[-45_2/0]_{\text{sym}}$  (Hollowell et al., *J Aircraft*, 1984)



# Aeroelastic optimization of a straight orthotropic wing

- ✓ Case of a straight wing made of an uncoupled orthotropic 16-ply laminate : polar domain ( $R_k - R_1$ ) for the bending tensor  $D$
- ✓ Case  $\Phi_1 = 0^\circ$ : orthotropic axis aligned with the wing axis

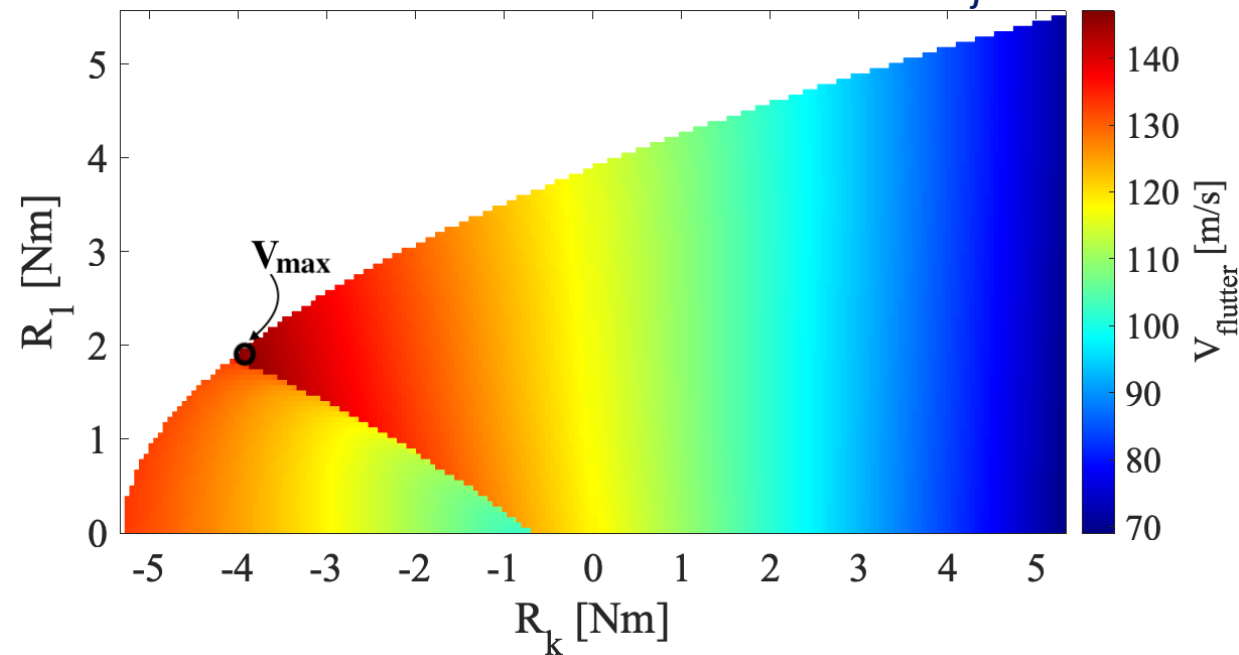
Model of the straight plate wing



Maximum flutter velocity

$$V_{\max} = 147 \text{ m/s}$$

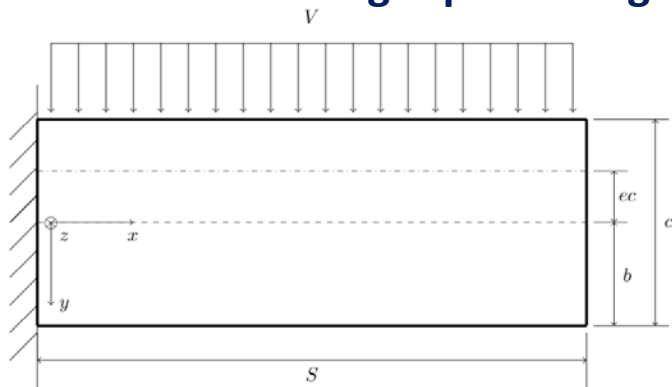
Response surface of flutter velocity  $V_f$



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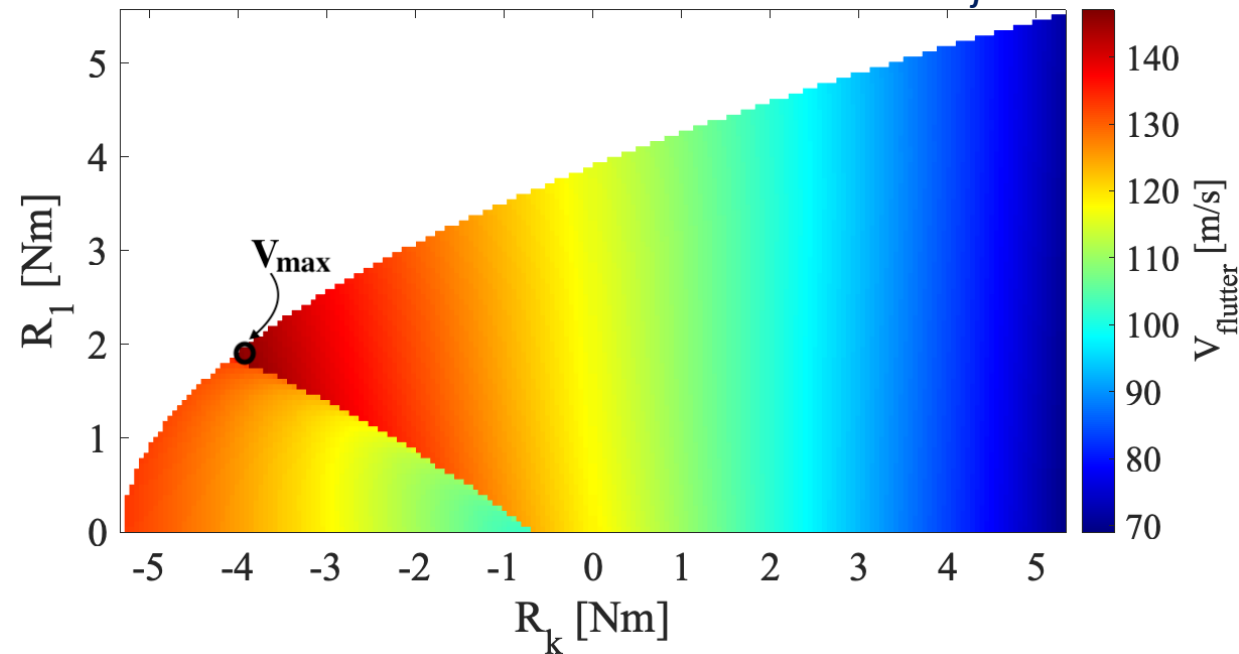
## Model of the straight plate wing



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## Response surface of flutter velocity $V_f$



- ✓ Maximum flutter velocity for an angle-ply orthotropic laminate with  $\alpha \approx 35^\circ$
- ✓ Improvement of  $V_f$ : appr. 25% wrt isotropic material and 50% wrt cross-ply
- ✓ Optimization wrt angle  $\Phi_1$ , cases of swept and tapered plate wings and anisotropy
- ✓ Discontinuity of critical flutter velocity due to mode-switch

# Influence of uncertainties on the aeroelastic response

- **Composite laminated wings** : **multiple sources of errors** (angles, thicknesses)
- Optimal configurations lay close to **discontinuities** : strongly affected by uncertainties



**Uncertainty quantification of flutter velocity wrt lamination errors**

(Nitschke et al, *Compos Struct* 2019)

- ✓ Use of the **polar formalism** to **reduce the dimension of the uncertain problem**

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- ✓ Analysis of **general uncertain stacking sequences** (unsymmetric and coupled)
- ✓ Only **6 uncertain polar parameters** represent **errors on angles and thicknesses** (instead of 2x16 laminate's uncertain constitutive parameters)



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- ✓ Only **6 uncertain polar parameters** represent **errors on angles and thicknesses** (instead of 2x16 laminate's uncertain constitutive parameters)
- ✓ Polar parameters are **correlated stochastic variables** : approximation of the uncertain function by a **polynomial chaos method** and **machine-learning techniques** for clustering configurations around the **discontinuity**

# Influence of uncertainties on the aeroelastic response

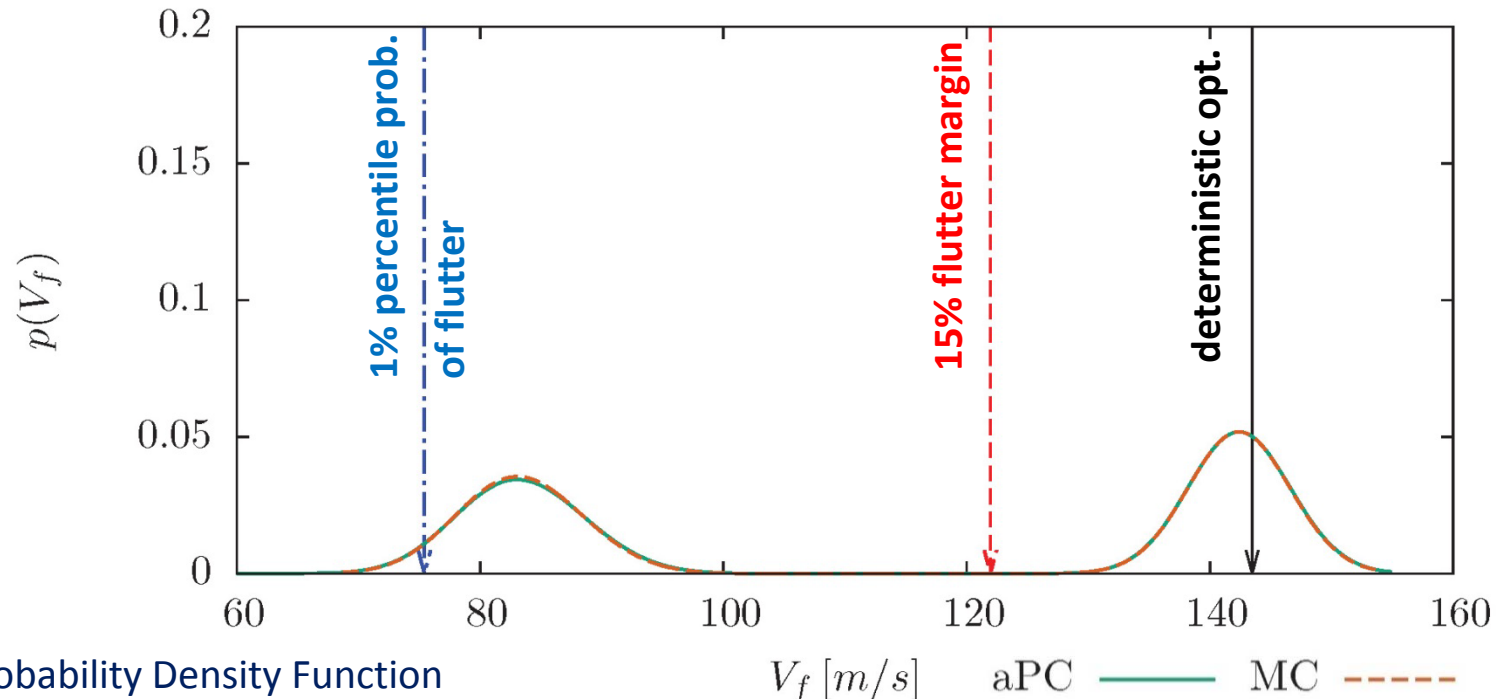
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## Uncertainty quantification of flutter velocity wrt lamination errors

(Nitschke et al, *Compos Struct* 2019)

- ✓ PDF<sup>(\*)</sup> function of  $V_f$  for the optimal deterministic configuration  
Errors on angles ( $\sigma_\alpha = 1^\circ$ ) and thicknesses ( $\sigma_t = 0.005$  mm)



(\*) PDF = Probability Density Function

# Conclusions

## Two-level polar approach to aeroelastic analysis of composite plate wings

- ✓ **Aeroelastic deterministic optimization :**
  - Case of constant stiffness (straight, swept and tapered plate wings)
  - Extension to the case of variable stiffness laminates (tow-steered)
- ✓ **Uncertainty quantification of the aeroelastic response :**
  - **general** coupled and unsymmetric **configurations**
  - influence of **errors in orientation angles and thicknesses** (similar approaches based on lamination parameters limited to symmetric distributions of errors on angles and do not consider errors on thicknesses)
- ✓ **Aeroelastic optimization in a stochastic framework :**
  - **Formulation of the optimization problem :** choice of aeroelastic functions
  - **Direct vs two-level approach :** how to take into account uncertainties at ply level ?
  - **Effect of lamination errors on polar components :** how to describe the correlation ?  
How to take into account the non-univocal relation of angles and elastic moduli ?

**Thank you for your attention !**



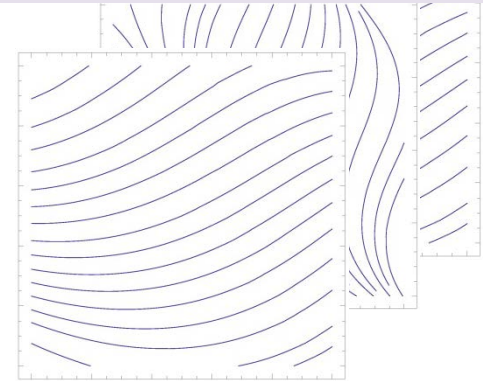
# Application to the optimization of tow-steered composites

**Tow-steered** = reinforced with **curvilinear fibers**



**Variable fields of anisotropic polar parameters**

$R_K(x,y)$ ,  $R_1(x,y)$  and  $\Phi_1(x,y)$



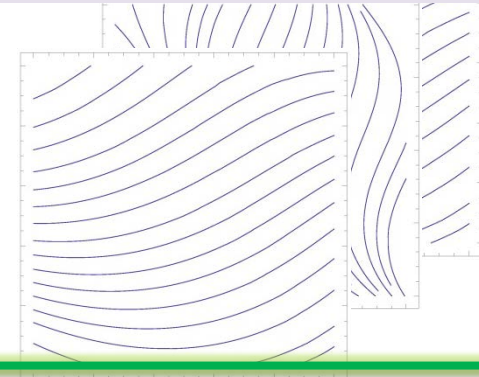
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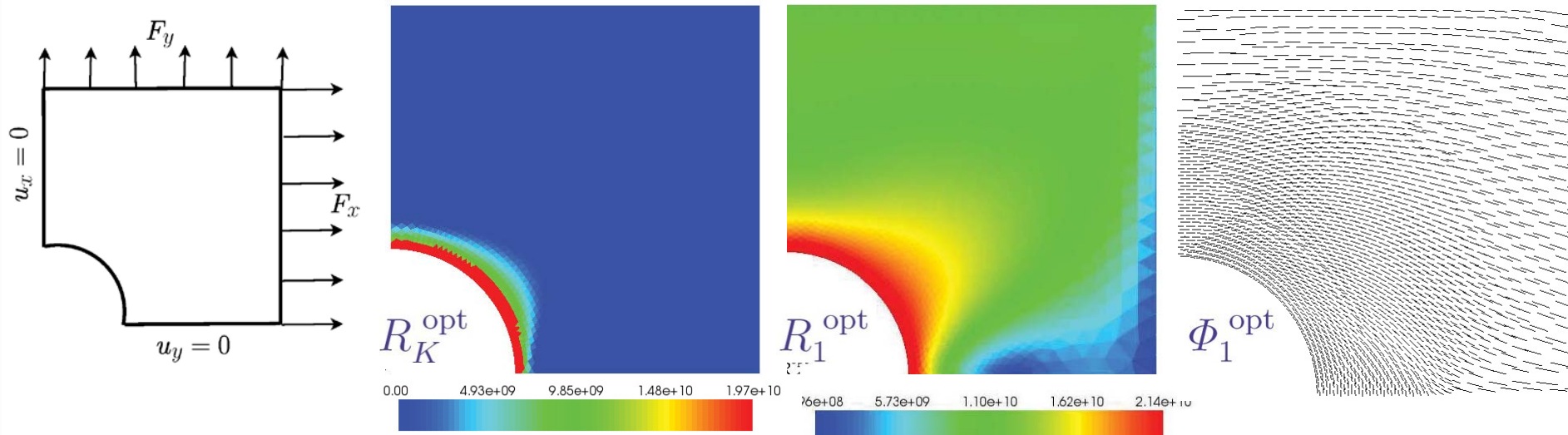


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## Compliance minimisation of tow-steered laminated structures



(C. Julien, *PhD thesis* 2010 ; Jibawy et al, *IJSS* 2011)

✓ Analytical minimisation of elastic energy for an orthotropic material [*JElas* 2010]

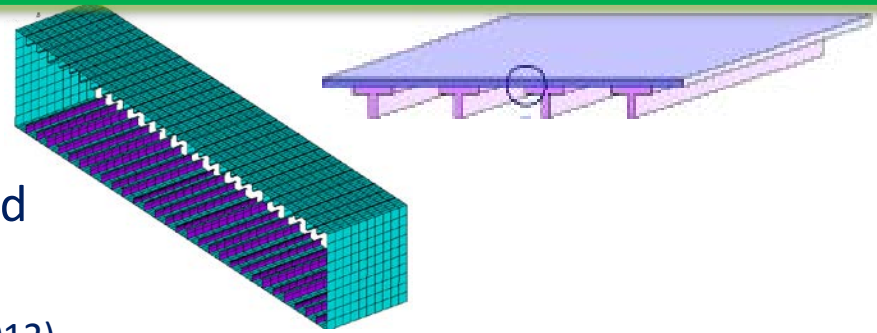


# Application to the optimization of modular structures

Weight minimisation of composite  
stiffened panels under buckling constraint

**Variables : thickness, material properties and  
number of constitutive modules**

(Montemurro, *PhD Thesis 2012* ; Montemurro et al, *JOTA 2012*)





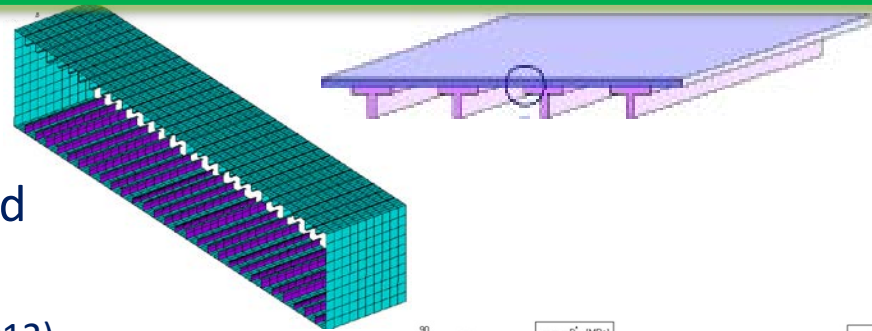
# Application to the optimization of modular structures

Weight minimisation of composite stiffened panels under buckling constraint

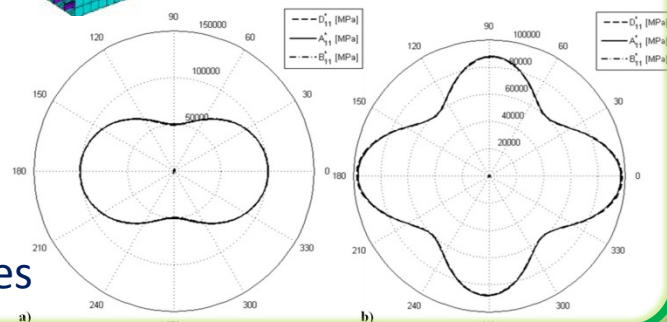
**Variables** : thickness, material properties and number of constitutive modules

(Montemurro, *PhD Thesis 2012* ; Montemurro et al, *JOTA 2012*)

- ✓ Coupling FEM and **genetic algorithm** with **variable number of chromosomes**
- ✓ Optimal stacking sequence retrieval by polar-genetic approach



Stiffner and skin optimal elastic properties



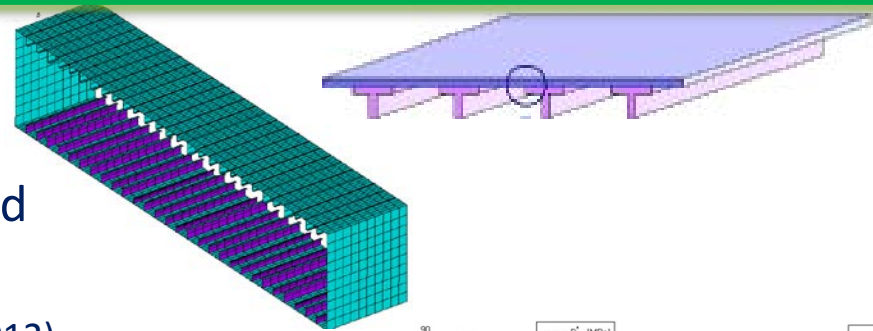
# Application to the optimization of modular structures

Weight minimisation of composite stiffened panels under buckling constraint

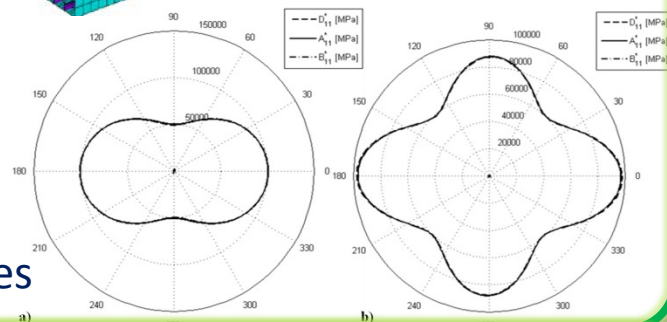
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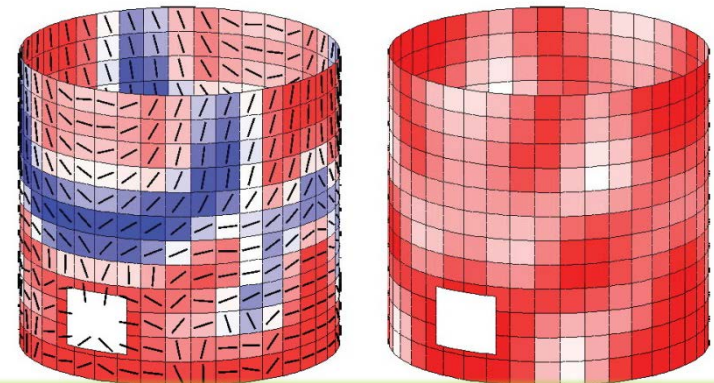
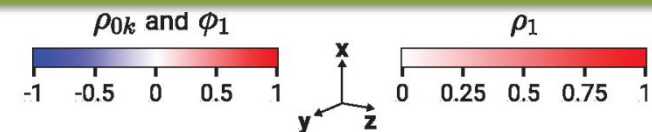
Stiffener and skin optimal elastic properties



Compliance minimisation of large composite stiffened aerospace structures under buckling and mass constraints

**Variables :** stiffening path, laminates' thickness and material properties

(F. Savine, *PhD thesis 2022*, collaboration with ONERA and CNES)





# My research contributions

1. Optimization of composite laminated plates
2. Optimization of variable-stiffness composite structures
3. Influence of anisotropy and uncertainties on non-linearities and instabilities

- i. Design of multistable composite shells

(Hamouche et al : *Meccanica* 2016, *PRSA* 2016 ; Brunetti et al : *IJSS* 2016, *Compos Struct* 2018)

PhD thesis of W. Hamouche (2013-16), post-doc M. Brunetti (2015-16)

Collaboration with C. Maurini (d'Alembert) and S. Vidoli (Univ Roma La Sapienza)

ANR project JC SLENDER 2014-18



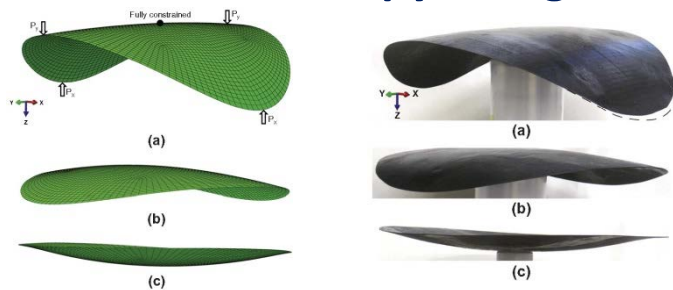
# Design of multistable composite shells

- ✓ Reduced non-linear models of orthotropic shells (Vidoli and Maurini, PRSA 2008)
- ✓ Application of the two-level approach based on the polar formalism
- ✓ Design of prescribed prestress fields (e.g. thermo- or hygro-elastic couplings)

# Design of multistable composite shells

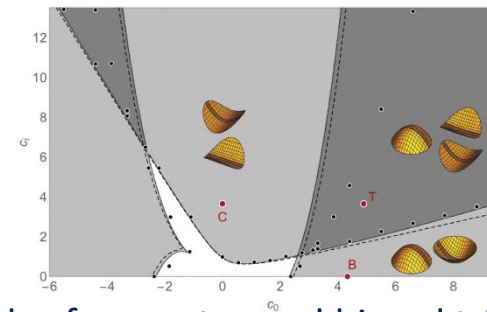
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## Effect of orthotropy and geometry



Design of a tristable composite shell at  
Bristol University (Coburn et al, *Compos Struct* 2013)

## Effect of geometry and prestress

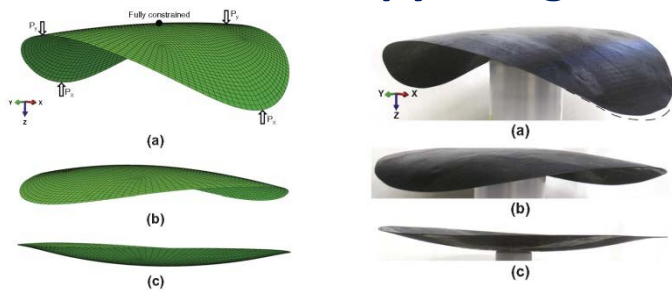


Design rules for prestressed bi- and tri-stable  
isotropic shells (Hamouche et al, *Meccanica* 2016)

# Design of multistable composite shells

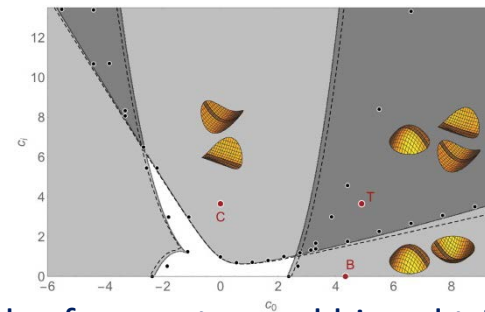
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## Effect of orthotropy and geometry



Design of a tristable composite shell  
Bristol University (Coburn et al, *Compos Struct* 2013)

## Effect of geometry and prestress



Design rules for prestressed bi- and tri-stable isotropic shells (Hamouche et al, *Meccanica* 2016)

## Effect of orthotropy, geometry and prestress

Bistability of clamped orthotropic shells (Brunetti et al, *Compos Struct* 2018)

