

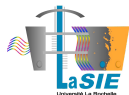
Vladimir Salnikov

CNRS & La Rochelle Université

# Structures de Dirac en Physique et Mécanique

Rencontre du GDR GDM  
à La Rochelle

26-28 Juin 2024



# Structures de Dirac en Physique et Mécanique

- Géométrie différentielle
  - symplectique, Poisson, Dirac
  - (un peu de) différentielle graduée
- Mécanique
  - dissipation / interaction ( $\supset$  SHP)
  - contraintes
  - approche variationnelle
- Physique
  - symmetries des fonctionnelles
  - jaugeage (et  $Q$ -cohomologie equivariante)
  - sigma-modèles

Géométrie  
généralisée  
(et graduée)

## Poisson manifold $\rightarrow (T^*[1]M, Q_\pi)$

Consider a Poisson manifold  $M$ ,  
 $\{\cdot, \cdot\}: C^\infty(M) \times C^\infty(M) \rightarrow C^\infty(M)$ .

A Poisson bracket can be written as  $\{f, g\} = \pi(df, dg)$ , where  $\pi \in \Gamma(\Lambda^2 TM)$  is a bivector field.  $\pi^{ij}(x) = \{x^i, x^j\}$ .

Consider  $T^*[1]M$  (coords.  $x^i(0), p_i(1)$ ), with a degree 1 vector field

$$Q_\pi = \left\{ \frac{1}{2} \pi^{ij} p_i p_j, \cdot \right\}_{T^*M} = \pi^{ij}(x) p_j \frac{\partial}{\partial x^i} - \frac{1}{2} \frac{\partial \pi^{jk}}{\partial x^i} p_j p_k \frac{\partial}{\partial p_i}$$

Jacobi identity:

$$\begin{aligned} \{f, \{g, h\}\} + \{g, \{h, f\}\} + \{h, \{f, g\}\} &= 0 \\ \Leftrightarrow [\pi, \pi]_{SN} &= 0 \Leftrightarrow Q_\pi^2 = 0 \end{aligned}$$

# Twisted Poisson structure

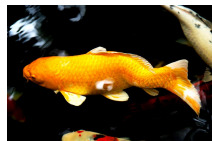
Consider a bivector field  $\pi \in \Gamma(\Lambda^2 TM)$ .

It defines an antisymmetric bracket  $\{f, g\} = \pi(df, dg)$ .

Let  $H \in \Omega_{cl}^3(M)$ .

A couple  $(\pi, H)$  defines a twisted Poisson structure if it satisfies the twisted Jacobi identity:

$$[\pi, \pi]_{SN} = \langle H, \pi \otimes \pi \otimes \pi \rangle$$



Consider  $T^*[1]M$  (coords.  $x^i(0), p_i(1)$ ), with a degree 1 vector field

$$Q_{\pi, H} = \pi^{ij}(x) p_j \frac{\partial}{\partial x^i} - \frac{1}{2} C_i^{jk}(x) p_j p_k \frac{\partial}{\partial p_i},$$

where  $C_i^{jk} = \frac{\partial \pi^{jk}}{\partial x^i} + H_{ij'k'} \pi^{j'j} \pi^{kk'}$ .

Twisted Jacobi identity  $\Leftrightarrow Q_{\pi, H}^2 = 0$



## Courant algebroids, Dirac structures

Let us construct on  $E = TM \oplus T^*M$  a twisted exact Courant algebroid structure, governed by a closed 3-form  $H$  on  $M$ .

The symmetric pairing:  $\langle v \oplus \eta, v' \oplus \eta' \rangle = \eta(v') + \eta'(v)$ ,

the anchor:  $\rho(v \oplus \eta) = v$

the  $H$ -twisted bracket (Dorfman):

$$[v \oplus \eta, v' \oplus \eta'] = [v, v']_{\text{Lie}} \oplus (\mathcal{L}_v \eta' - \iota_{v'} d\eta + \iota_v \iota_{v'} H).$$

## Courant algebroids, Dirac structures

A Courant algebroid (Liu, Weinstein, and Xu; Courant) is a vector bundle  $E \rightarrow M$  equipped with the following operations: a symmetric non-degenerate pairing  $\langle \cdot, \cdot \rangle$  on  $E$ , an  $\mathbb{R}$ -bilinear bracket  $[\cdot, \cdot] : \Gamma(E) \otimes \Gamma(E) \rightarrow \Gamma(E)$  on sections of  $E$ , and an anchor  $\rho$  which is a bundle map  $\rho : E \rightarrow TM$ , satisfying the axioms:

$$\begin{aligned}\rho(\varphi) \langle \psi, \psi \rangle &= 2 \langle [\varphi, \psi], \psi \rangle, \\ [\varphi, [\psi_1, \psi_2]] &= [[\varphi, \psi_1], \psi_2] + [\psi_1, [\varphi, \psi_2]], \\ 2[\varphi, \varphi] &= \rho^*(d \langle \varphi, \varphi \rangle),\end{aligned}$$

where  $\rho^* : T^*M \rightarrow E$  (identifying  $E$  and  $E^*$  by  $\langle \cdot, \cdot \rangle$ ).

**Theorem.** (D. Roytenberg) Courant algebroids  $\leftrightarrow$  degree 2 symplectic manifolds with compatible  $Q$ -structures.

**Theorem.** (P. Ševera) Exact ( $\rho$  surjective,  $rk E = 2 \dim M$ ) Courant algebroids are classified by  $H_{dR}^3(M)$ .

## Courant algebroids, Dirac structures

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The symmetric pairing:  $\langle v \oplus \eta, v' \oplus \eta' \rangle = \eta(v') + \eta'(v)$ ,

the anchor:  $\rho(v \oplus \eta) = v$

the  $H$ -twisted bracket (Courant – Dorfman):

$$[v \oplus \eta, v' \oplus \eta'] = [v, v']_{\text{Lie}} \oplus (\mathcal{L}_v \eta' - \iota_{v'} d\eta + \iota_v \iota_{v'} H). \quad (1)$$

A Dirac structure  $\mathcal{D}$  is a maximally isotropic (Lagrangian) subbundle of an exact Courant algebroid  $E$  closed with respect to the bracket (1).

Trivial example:  $\mathcal{D} = TM$  for  $H = 0$ .



↑ if not – almost Dirac

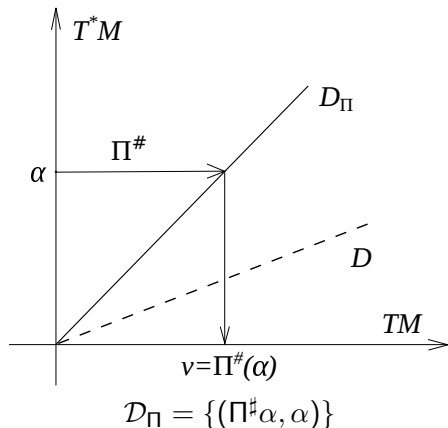


## Dirac structures: Poisson example.

**Example.**  $\mathcal{D} = \text{graph}(\Pi^\sharp)$

Isotropy  $\Leftrightarrow$   
 $\pi^{ij}$  antisymmetric.

Involutivity  $\Leftrightarrow$   
 $\Pi$  (twisted) Poisson.

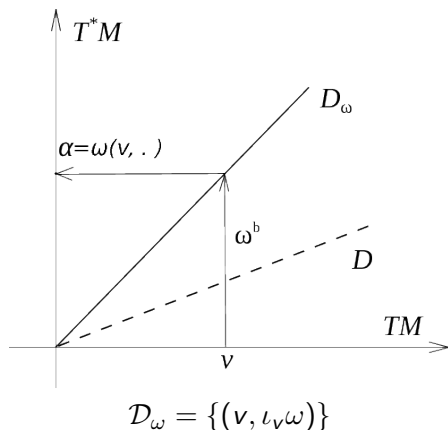


## Dirac structures: (pre)symplectic example.

**Example.**  $\mathcal{D} = \text{graph}(\omega)$

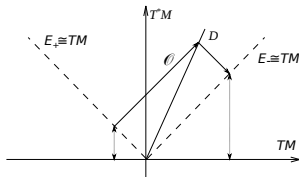
Isotropy  $\Leftrightarrow$   
 $\omega_{ij}$  antisymmetric.

Involutivity  $\Leftrightarrow$   
 $\omega$  closed.



## Dirac structures: general

Choose a metric on  $M \Rightarrow TM \oplus T^*M \cong TM \oplus TM$ ,  
 Introduce the eigenvalue subbundles  $E_{\pm} = \{v \oplus \pm v\}$   
 of the involution  $(v, \alpha) \mapsto (\alpha, v)$ . Clearly,  $E_+ \cong E_- \cong TM$ .



(Almost) Dirac structure – graph of an  
 orthogonal operator  $O \in \Gamma(\text{End}(TM))$ :  
 $(v, \alpha) = ((\text{id} - O)w, g((\text{id} + O)w, \cdot))$   
Dirac structure = almost Dirac +  
 (Jacobi-type) integrability condition:

$$g\left(\mathcal{O}^{-1} \nabla_{(\text{id}-\mathcal{O})\xi_1} (\mathcal{O})\xi_2, \xi_3\right) + \text{cycl}(1, 2, 3) = \frac{1}{2} H((\text{id} - \mathcal{O})\xi_1, (\text{id} - \mathcal{O})\xi_2, (\text{id} - \mathcal{O})\xi_3).$$

**Remark (!)** Any  $\mathcal{D}[1]$  can be equipped with a  $Q$ -structure

$$Q = (1 - O)_{i'j'}^{i''} a^{i''} \frac{\partial}{\partial x^i} + \frac{1}{2} C_{jk}^i a^j a^k \frac{\partial}{\partial a^i}, \text{ with}$$

$$C_{jk}^i = (1 - O)_j^m \Gamma_{mk}^i - (j \leftrightarrow k) + O_k^{m;i} O_{mj} + \frac{1}{2} H_{j'k'}^i (1 - O)_j^{j'} (1 - O)_k^{k'}.$$

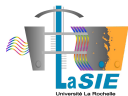
**and/or** Lie algebroid structure inherited from Courant algebroid.

(Histoire de la)

Mécanique

# Préservation des structures de la géométrie généralisée en calcul numérique 2/3

Vladimir Salnikov



“Paris”, 6 Novembre 2020



Groupement de Recherche  
Géométrie Différentielle et Mécanique

Year 0 AC

Geometry encodes the physics of the system

Philosophy:

Razafindralandy  
de Saxcé, Carré

Falaise  
Hilic, Roze

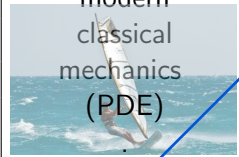
Hubert

Lozienco

Ryvkin, Laurent-G.



classical  
classical  
mechanics  
(ODE)



modern  
classical  
mechanics  
(PDE)

Mechanical property	conservation of energy	symmetries	dissipation / interaction power balance; constraints control	conservation of energy	symmetries	dissipation / interaction	$rot(grad) = 0, div(rot) = 0$	control
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Geometric description	Poisson / symplectic	Lie groups/algebras, Cartan moving frames	(almost) Dirac	(singular) foliations	multisymplectic	Cartan moving frames	Stokes-Dirac	$d^2 = 0$ - DEC	foliations
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F  
G  
M

Ryvkin

Ayoub

1) DG/Q varieties

# Open questions

Near at hand:

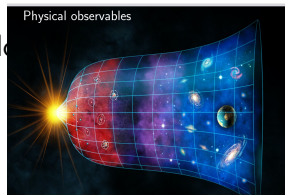
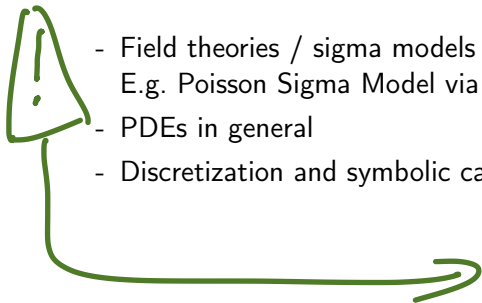
- Poisson integrators
- Dynamics for general Dirac structures
- Application to control theory

→ Cosserat

→ CLKRS

Slightly further away

- Field theories / sigma models for mechanics and beyond.  
E.g. Poisson Sigma Model via n-plectic geometry.
- PDEs in general
- Discretization and symbolic calc

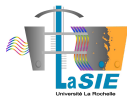


Contraintes  
(liaisons)



# Dynamique de Dirac pour les problèmes mécaniques

Vladimir Salnikov  
CNRS & La Rochelle University



NANTES | 29 AOÛT - 2 SEPT. 2022

**Congrès Français de Mécanique**

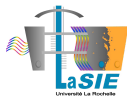


# Pseudo-geometric integrators

(Daria Loziienko)

Vladimir Salnikov

CNRS & La Rochelle University



NANTES | 29 AOÛT - 2 SEPT. 2022

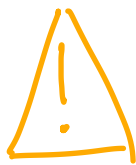
**Congrès Français de Mécanique**



## Other remarks / work in progress

1. We understood why Marsden inspired method was not really geometric.

1.bis it was pseudo-geometric of order (1,2)



holonomic

vs

non-holonomic

2. Dirac-2 was not much better: something like order (1,2 ; 2,3)

3. TODO: I still want it to be (honestly) variational

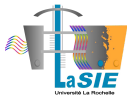
# Approche variationnelle de la dynamique de Dirac

Vladimir Salnikov

*not  
almost*



ENS-PS, 25 Novembre 2022



Dissipation /  
interaction

# Systemes Hamiltoniens à ports apprentissage et un peu de Dirac

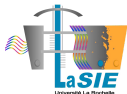


PHS

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Benjamin  
!



Journée GdR GDM,  
IRCAM, 7 mai 2024

## Learning the PHS structure – some remarks

- First step – Machine Learning methods.

Proof of concept – OK.

Hamiltonian VS generic training ? *Need hands*  *Success criteria?*

- Second step – “catalog” of symplectic / Poisson structures, computation of cohomologies and compatible vector fields.
- Maybe a new way of defining **canonical forms of systems of differential equations.**



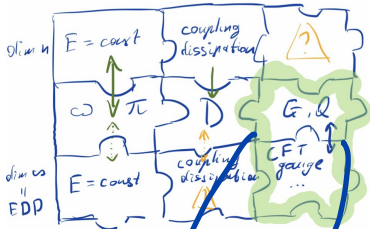
Physique



# Previous episodes

# (Paris '23)

Instead of conclusion – big puzzle and questions



And what precisely about mechanics? What phenomena?

La Rochelle, France, 08/07/2021, 11:40



skip recap

1.1.7. Restrictions on the Lagrange Multipliers	13
1.1.8. Irreducible and Reducible Cases	14
1.1.9. Total Hamiltonian	
1.1.10. First-Class and Second-Class Constraints as Gauge Transformations	
1.2. Transformations That Do Not Change the Physical State. Gauge Transformations	
1.2.1. A Counterexample to the Extended Action Principle	21
1.2.2. The Extended Hamiltonian	
1.2.3. The Extended Action Principle	21
1.2.4. The Dirac Bracket	21

**Gauge Systems**  
Marc Henneaux and Claudio Teitelboim

Quarks  
SU(3) symmetry

8 connection 1-forms

miltonian Systems	3
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ian	9
itonian Form	11
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	14

Important "tool":  
graded geometry,  
differential graded  
manifolds.

## Equivariant cohomology and gauging in a nutshell

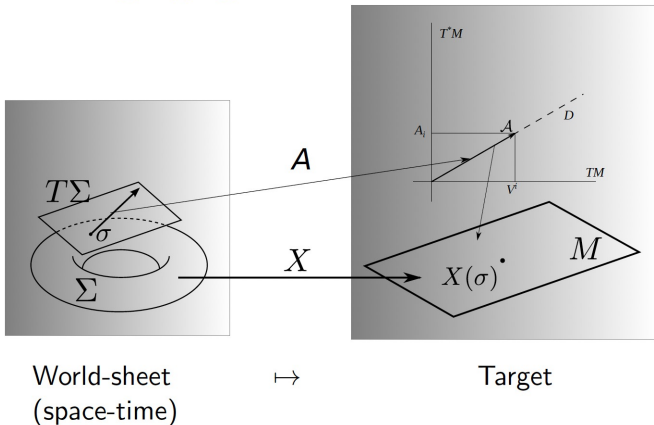
"equations of motion" ↔ Q-morphisms  
"symmetries" ↔ Q-homotopies  
"gauge invariant" ↔ "equivariantly Q-closed"

## Flashback to Vladimir's childhood

Saclay 25/11/2022

Jaugeage  
des sigma  
modèles

# Sigma models, gauging



Simple examples

$$B \in \Omega^2(M)$$

or

$$H \in \Omega^3(M)$$

$$S = \int_{\Sigma} X^* B$$

$$S = \int_{\Sigma_3} X^* H$$

## Sigma model example – gauging problem

$$S[X] := \int_{\Sigma} X^* B$$

$B \in \Omega(M)$ ,  $\dim(\Sigma) = d = \deg(B)$ .

Assume that there is a Lie group  $G$  acting on  $M$  that leaves  $B$  invariant. It induces a  $G$ -action on  $M^{\Sigma}$ , which leaves  $S$  invariant.

The functional  $S$  is called (locally) gauge invariant, if it is invariant even with respect to the group  $G^{\Sigma} \equiv C^{\infty}(\Sigma, G)$ ; the invariance w.r.t.  $G$  is called a rigid (global) invariance.

Extending the functional  $S$  to a functional  $\tilde{S}$  defined on  $(X, A) \in M^{\Sigma} \times \Omega^1(\Sigma, \mathfrak{g})$  by means of so-called minimal coupling,

$$\tilde{S}_{2D}[X, A] := \int_{\Sigma} \left( X^* B - A^a X^* \iota_{v_a} B + \frac{1}{2} A^a A^b X^* \iota_{v_a} \iota_{v_b} B \right).$$

# Example: (part of) the Standard Model



Quarks

$SU(3)$  symmetry

$\Rightarrow \Rightarrow$

$\Rightarrow \Rightarrow$

$G = SU(3) \times SU(2) \times U(1)$

$\Rightarrow \Rightarrow$

$\Rightarrow \Rightarrow$



8 connection 1-forms

Gluons

LET THE  
 Lieber Papa  
 ich habe Dich so  
 doll LIEB und  
 umarme Dich ganz  
 Rest! Bude!!!  
 Deine Sybil  
 Vels  
 sumo  
 nach up

## Equivariant cohomology for $Q$ -manifolds

Let  $(\mathcal{M}, Q)$  be a  $Q$ -manifold, and let  $\mathcal{G}$  be a subalgebra of the algebra of degree  $-1$  commuting vector fields  $\varepsilon$  on  $\mathcal{M}$ , which is closed w.r.t. the  $Q$ -derived bracket:  $[\varepsilon, \varepsilon']_Q = [\varepsilon, [Q, \varepsilon']]$ .

**Definition.** Call a differential form (superfunction)  $\omega$  on  $\mathcal{M}$   $\mathcal{G}$ -horizontal if  $\varepsilon\omega = 0$ , for any  $\varepsilon \in \mathcal{G}$ .

**Definition.** Call a differential form (superfunction)  $\omega$  on  $\mathcal{M}$   $\mathcal{G}$ -equivariant if  $(ad_Q\varepsilon)\omega := [Q, \varepsilon]\omega = 0$ , for any  $\varepsilon \in \mathcal{G}$ .

**Definition.** Call a differential form (superfunction)  $\omega$  on  $\mathcal{M}$   $\mathcal{G}$ -basic if it is  $\mathcal{G}$ -horizontal and  $\mathcal{G}$ -equivariant.

**Remark.** For  $Q$ -closed superfunctions  $\mathcal{G}$ -horizontal  $\Leftrightarrow \mathcal{G}$ -basic

**Remark.** Usual equivariant cohomology can be recovered.

**Key idea to apply to gauge theories:**

Replace “gauge invariant” by “equivariantly  $Q$ -closed”

## Poisson sigma model

World-sheet:  $\Sigma$  (closed, orientable, with no boundary,  $\dim = 2$ ).

Target: Poisson manifold  $(M, \pi)$ . The functional is defined over the space of vector bundle morphisms  $T\Sigma \rightarrow T^*M$

Field content: scalar fields  $X^i : \Sigma \rightarrow M$  and 1-form valued (“vector”) fields:  $A_i \in \Omega^1(\Sigma, X^*T^*M)$ .

The action functional:  $S = \int_{\Sigma} A_i \wedge dX^i + \frac{1}{2} \pi^{ij} A_i \wedge A_j$ ,

Equations of motion:

$$\begin{aligned}dX^i + \pi^{ij} A_j &= 0, \\dA_i + \pi_{,i}^{jk} A_j A_k &= 0.\end{aligned}$$

Gauge transformations (complicated !):

$$\begin{aligned}\delta_{\varepsilon} X^i &= \pi^{ij} \varepsilon_j, \\ \delta_{\varepsilon} A_i &= d\varepsilon_i + \pi_{,i}^{jk} A_j \varepsilon_k\end{aligned}$$

where  $\varepsilon = \varepsilon_i dX^i \in \Gamma(X^*T^*M)$  a 1-form.

## Gauging the Wess–Zumino term

WZ-term:  $H \in \Omega^{\dim \Sigma + 1}(M)$ ,  $dH = 0$ ,  $\partial \tilde{\Sigma} = \Sigma$ ,

$$S[X] := \int_{\tilde{\Sigma}} X^* H$$

Obstructions to gauging:

B. de Wit, C. Hull, M. Rocek “New topological terms in gauge invariant action” ('87)

C. M. Hull and B. J. Spence, “The Gauged Nonlinear  $\sigma$  Model With Wess-Zumino Term” ('89)

C. M. Hull and B. J. Spence, “The Geometry of the gauged sigma model with Wess-Zumino term” ('91)

Upshot: Gauging of such a WZ-term is possible, if and only if  $H$  permits an equivariantly closed extension. (J.M. Figueroa-O'Farrill and S. Stanciu, '94)

Limitation: number of gauge fields =  $\dim G$ .



## Equivariant cohomology

A Lie group  $G$  acting on a smooth manifold  $M$ .  $\Omega^\bullet(M/G)$  – ?

First assume that  $G$  acts freely on  $M$ , i.e.  $M/G$  is a topological space. Consider  $p: M \rightarrow M/G$ ,  $\omega_0 \in \Omega^\bullet(M/G)$ .  $\omega = p^*(\omega_0)$  is well defined,  $\omega$  is called basic.

Property (defining) of a basic form:  $\iota_v \omega = 0$ ,  $\mathcal{L}_v \omega = 0$ ,  $v \in \mathcal{G}$ .

Equivariant differential(s):  $\tilde{d} = (d + \iota_v)$ .  $\tilde{d}^2|_{basic} = 0$

If the group does not act freely one can still perform a similar construction but modifying the manifold  $M \rightarrow M \times EG \rightarrow$  huge space of differential forms, but not in cohomology. Instead one considers the Weil model or the Cartan model of equivariant cohomology, by defining the action on the Lie algebra valued connections (of degree 1) and curvatures (of degree 2) with some compatibility conditions.

**Remark.**  $d$  increases the form degree,  $\iota_v$  decreases.

## Equivariant cohomology for $Q$ -manifolds

Let  $(\mathcal{M}, Q)$  be a  $Q$ -manifold, and let  $\mathcal{G}$  be a subalgebra of the algebra of degree  $-1$  commuting vector fields  $\varepsilon$  on  $\mathcal{M}$ , which is closed w.r.t. the  $Q$ -derived bracket:  $[\varepsilon, \varepsilon']_Q = [\varepsilon, [Q, \varepsilon']]$ .

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**Definition.** Call a differential form (superfunction)  $\omega$  on  $\mathcal{M}$   $\mathcal{G}$ -equivariant if  $(ad_Q\varepsilon)\omega := [Q, \varepsilon]\omega = 0$ , for any  $\varepsilon \in \mathcal{G}$ .

**Definition.** Call a differential form (superfunction)  $\omega$  on  $\mathcal{M}$   $\mathcal{G}$ -basic if it is  $\mathcal{G}$ -horizontal and  $\mathcal{G}$ -equivariant.

**Remark.** For  $Q$ -closed superfunctions  $\mathcal{G}$ -horizontal  $\Leftrightarrow \mathcal{G}$ -basic

**Key idea to apply to gauge theories:**

Replace gauge invariant by equivariantly  $Q$ -closed

## Gauge transformations of the PSM

$$\begin{array}{ccc}
 & T[1]\Sigma \times T[1]T^*[1]M \circlearrowleft (d\Sigma + d + \mathcal{L}_{Q_\pi}) & \\
 & \nearrow \hat{f} & \downarrow \\
 T[1]\Sigma \circlearrowleft d\Sigma & \xrightarrow{\hat{a}} & T[1]\Sigma \times T^*[1]M \circlearrowleft d\Sigma + Q_\pi
 \end{array}$$

Functional:  $S_{PSM} = \int_{\Sigma^3} \hat{f}^*(dp_i dx^i)$ .

E.o.m.:  $\hat{f}^*(dx^i) = 0$ ,  $\hat{f}^*(dp_i) = 0$ .

Degree  $-1$  vector field on  $T^*[1]M$ :  $\varepsilon = \varepsilon_i \frac{\partial}{\partial p_i}$

$\rightarrow$  1-form on  $M$ :  $\varepsilon = \varepsilon_i dx^i$

Canonical lift to  $T[1]T^*[1]M$ :  $\tilde{\varepsilon} = \mathcal{L}_\varepsilon$ .

Gauge transformations:  $\hat{f}^*([\hat{Q}, \hat{\varepsilon}] \cdot)$ . Invariance  $\Leftrightarrow$   $d\varepsilon = 0$

(cf. M.Bojowald, A.Kotov, T.Strobl '04; A.Kotov, T.Strobl '07).

## (Twisted) Poisson sigma model

PSM (P.Schaller and T.Strobl, N.Ikeda – 1994)

Functional on vector bundle morphisms from  $T\Sigma$  to  $T^*M$ , where  $(M, \pi)$  Poisson.

Twisted PSM, PSM with background

(C.Klimcik and T.Strobl, J.-S.Park – 2002)

Functional on vector bundle morphisms from  $T\Sigma$  to  $T^*M$ , where  $(M, (\pi, H))$  twisted Poisson.

$$S_{HPSM} = S_{PSM} + \int_{\Sigma^{(3)}} X^*(H)$$

where  $\partial\Sigma^{(3)} = \Sigma$ ,  $H \neq 0 \Rightarrow$  Wess-Zumino term.

## Gauge transformations of the twisted PSM

**Theorem (V.S., T.Strobl)** Any smooth map from  $\Sigma$  to the space  $\Gamma(T^*M)$  of sections of the cotangent bundle to a twisted Poisson manifold  $M$  defines an infinitesimal gauge transformation of the twisted PSM governed by  $(\pi, H)$  in the above sense, if and only if for any point  $\sigma \in \Sigma$  the section  $\varepsilon \in \Gamma(T^*M)$  satisfies

$$d\varepsilon - \iota_{\pi\#\varepsilon}H = 0$$

where  $d$  is the de Rham differential on  $M$ .

## Dirac sigma model

Dirac sigma model (A.Kotov, P.Schaller, T.Strobl – 2005)

Functional on vector bundle morphisms from  $T\Sigma$  to  $\mathcal{D}$ .

(Generalizes twisted PSM and G/G WZW model).

$$S_{DSM}^0 = \int_{\Sigma} g(dX, \wedge (1 + \mathcal{O})A) + g(A, \wedge \mathcal{O}A) + \int_{\Sigma_3} H.$$

**Important remark:** Vector bundle morphisms  $\rightarrow$  degree preserving maps between graded ( $Q$ -) manifolds

## Gauge transformations of the DSM

**Theorem (V.S., T.Strobl)** Any smooth map from  $\Sigma$  to the space  $\Gamma(\mathcal{D})$  of sections of the Dirac structure  $\mathcal{D} \subset TM \oplus T^*M$  defines an infinitesimal gauge transformation of the (metric independent part of the) Dirac sigma model governed by  $\mathcal{D}$  in the above sense, if and only if for any point  $\sigma \in \Sigma$  the section  $\nu \oplus \eta \in \Gamma(\mathcal{D})$  satisfies

$$d\eta - \iota_\nu H = 0$$

where  $d$  is the de Rham differential on  $M$ .

**Remark 1.**  $H$  non-degenerate – 2-plectic geometry.

**Remark 2.** Hydrodynamics (stationary Lamb equation).

## Extension of the gauge algebra

**Proposition.** The Lie algebra  $(\tilde{\mathcal{G}}, [ , ]_{\tilde{\mathcal{Q}}})$  of degree  $-1$  commuting vector fields, generalizing the  $\mathcal{L}$ . lift, is isomorphic to the semi-direct product of Lie algebras  $\mathcal{G} \in \mathcal{A}$ , where  $\mathcal{G}$  is a Lie algebra of 1-forms  $T^*[1]M$  with the bracket

$$[\varepsilon^1, \varepsilon^2] = \mathcal{L}_{\pi^\# \varepsilon^1} \varepsilon^2 - \mathcal{L}_{\pi^\# \varepsilon^2} \varepsilon^1 - d(\pi(\varepsilon^1, \varepsilon^2)) + \iota_{\pi^\# \varepsilon^1} \iota_{\pi^\# \varepsilon^2} H,$$

obtained from the (twisted) Lie algebroid of  $T^*M$  (anchor =  $\pi^\#$ );  $\mathcal{A}$  is a Lie algebra of covariant 2-tensors on  $M$  with a bracket

$$[\bar{\alpha}, \bar{\beta}] = \langle \pi^{23}, \bar{\alpha} \otimes \bar{\beta} - \bar{\beta} \otimes \bar{\alpha} \rangle,$$

(the upper indices “23” of  $\pi$  stand for the contraction on the 2d and 3rd entry of the tensor product);

$\mathcal{G}$  acts on  $\mathcal{A}$  by

$$\rho(\varepsilon)(\bar{\alpha}) = \mathcal{L}_{\pi^\# \varepsilon}(\bar{\alpha}) - \langle \pi^{23}, (d\varepsilon - \iota_{\pi^\# \varepsilon} H) \otimes \bar{\alpha} \rangle.$$



## Gauging $\rightarrow$ twisted Poisson sigma model

Consider a subalgebra  $\mathcal{GT} \subset \tilde{\mathcal{G}}$  defined by

$$\begin{aligned}d\varepsilon - \iota_{\pi\#\varepsilon}H &= 0 \\ \bar{\alpha}^A &= 0.\end{aligned}$$

**Theorem (V.S., T.Strobl).** Consider the graded manifold  $\mathcal{M} = T[1]T^*[1]M$ , equipped with the  $Q$ -structure  $\tilde{Q} = \tilde{Q}_\pi$ , governed by an  $H$ -twisted Poisson bivector  $\Pi$ , such that the pull-back of  $H$  to a dense set of orbits of  $\Pi$  is non-vanishing. The  $\mathcal{GT}$  equivariantly closed extension of the given 3-form  $H$  defines uniquely the functional of the twisted Poisson sigma model.

**Remark.** Non-degeneracy of the pull-back of  $H$  is a sufficient condition; PSM is obtained by gauging a vanishing 3-form.

## Gauging $\rightarrow$ Dirac sigma model

Consider a subalgebra  $\mathcal{GT} \subset \tilde{\mathcal{G}}$  defined by

$$\begin{aligned}d\eta - \iota_\nu H &= 0 \\ \tilde{\alpha}^A &= 0.\end{aligned}$$

### Theorem (V.S., T.Strobl).

Let  $H$  be a closed 3-form on  $M$  and  $D$  a Dirac structure on  $(TM \oplus T^*M)_H$  such that the pullback of  $H$  to a dense set of orbits of  $D$  is non-zero. Then the  $\mathcal{GT}$ -equivariantly closed extension  $\tilde{H}$  of  $H$  is unique and  $\int_{\Sigma^3} f^*(\tilde{H})$  yields the (metric-independent part of) the Dirac sigma model on  $\Sigma = \partial\Sigma^3$ .

V.S., T.Strobl, “Dirac Sigma Models from Gauging”, Journal of High Energy Physics, 11(2013)110.

V.S. “Graded geometry in gauge theories and beyond”, Journal of Geometry and Physics, Volume 87, 2015.

## Generality of the DSM in $\dim = 2$ .

Standard gauging: introduce Lie algebra valued 1-forms  $A^a e_a \in \Omega^1(\Sigma, \mathfrak{g})$ .

Lie algebra acting on the target  $\Rightarrow e_a \mapsto v_a \in \Gamma(TM)$ .

Rigid invariance  $\Rightarrow e_a \mapsto \alpha_a \in \Gamma(T^*M)$

Composite gauge fields:

$(V, A) = (v_a A^a, \alpha_a A^a) \in \Omega^1(\Sigma, X^*(TM \oplus T^*M))$ .

$V$  and  $A$  are dependent  $\Rightarrow$  isotropy condition.

Gauge transformations  $\Rightarrow$  integrability condition.

## Generality of the DSM in $\dim = 2$ , details

Courant algebroid:  $E = TM \oplus T^*M$

Pairing:  $\langle v \oplus \eta, v' \oplus \eta' \rangle = \eta(v') + \eta'(v)$ ,

Anchor:  $\rho(v \oplus \eta) = v$

$[v \oplus \eta, v' \oplus \eta'] = [v, v']_{\text{Lie}} \oplus (\mathcal{L}_v \eta' - \iota_{v'} d\eta + \iota_v \iota_{v'} H)$ . (\*)

$Q$ -symplectic realization:  $T^*[2]T[1]M(p_i(1), \psi_i(2), \theta^i(1), x^i(0))$ .

(cf. Roytenberg)

$Q = \{Q, \cdot\}$ , where  $Q = \theta^i \psi_i + \frac{1}{6} H_{ijk} \theta^i \theta^j \theta^k$  and

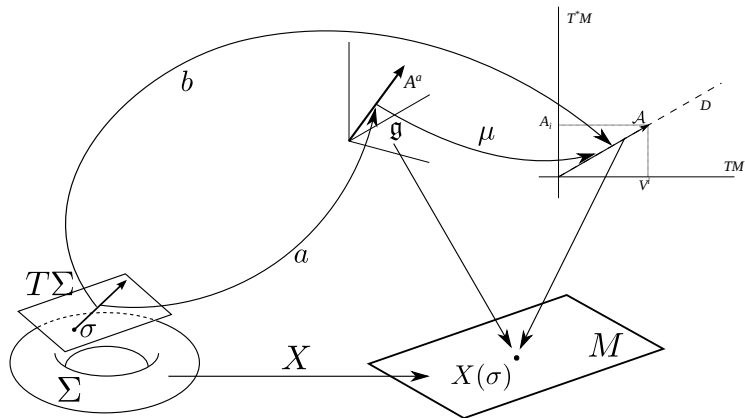
$\epsilon = \eta_i \theta^i + v^i p_i$ ,  $\epsilon = \{\epsilon, \cdot\}$ .  $[\epsilon, \epsilon']_Q \Leftrightarrow (*)$

To recover  $(A, V)$  gauge transformations, consider

$T[1]E$ ,  $\tilde{Q} = d + \mathcal{L}_Q$ ,  $\tilde{\epsilon} = \mathcal{L}_\epsilon$ .

$A_i = f^*(p_i)$ ,  $V^i = f^*(\theta^i) \Rightarrow \dots \Rightarrow \dots \Rightarrow \text{DSM}$

## Generality of the DSM in $\dim = 2$ .



A.Kotov, V.S., T.Strobl, "2d Gauge theories and generalized geometry", Journal of High Energy Physics, 08(2014)021.

Et bien

on

observe !

# Alekseev - Chekeres

## Poisson $\sigma$ -model for a ~~Wilson~~ surface

- View Wilson surface action as a version of the action  $S_{\omega_0}$  interacting with the external gauge field  $A$ .

### Poisson $\sigma$ -model version of the action

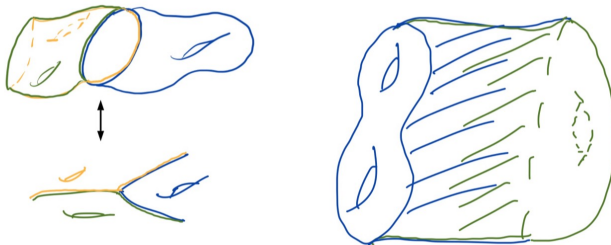
$$S_\sigma(b, A, \alpha) = \int_\Sigma \text{Tr } b (F_A + (d_A g g^{-1} + \alpha)^2 - (d_A g g^{-1})^2).$$

### Poisson $\sigma$ -model as a BF theory

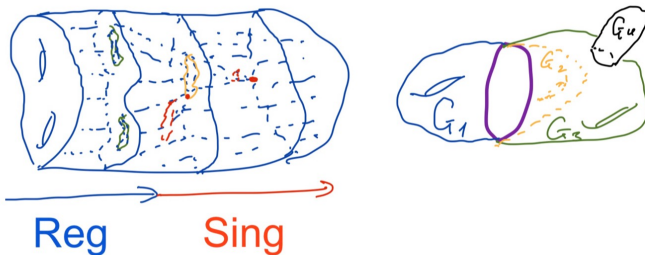
$$S_\sigma(b, A, \alpha) = \int_\Sigma \text{Tr } b F_{A+\alpha},$$

where the field  $b$  is constrained and  $A + \alpha$  is a new connection on  $P$ .

# Généralisations de Wilson surfaces en 2d et SUSY



Interaction proche et distante



Interactions continues et systèmes multivers



Merci



pour votre attention !

# Publicité :

1)



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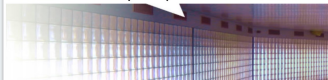
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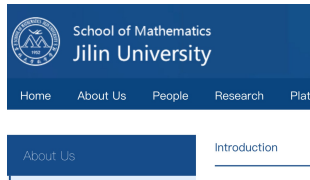
On s'intéresse souvent en mécanique aux problèmes directs consistant à chercher le champ de déplacements ou de vitesses, connaissant les caractéristiques du solide ou du fluide ainsi que les conditions aux limites et les efforts que subit le milieu continu. On se

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et encore merci !

