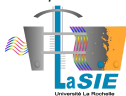


# Formulation géométrique de la mécanique: histoire, philosophie, religion...

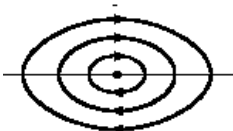

Vladimir Salnikov



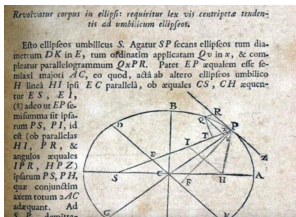
La Rochelle, 8 Juillet 2021



## Very classical story

<p>Canonical case: given <math>H: T^*Q \rightarrow \mathbb{R}</math></p> $\dot{\mathbf{q}} = \frac{\partial H}{\partial \mathbf{p}}, \quad \dot{\mathbf{p}} = -\frac{\partial H}{\partial \mathbf{q}}$	<p>Symplectic geometry</p> $\omega = \sum_i dp_i \wedge dq^i$ $\iota_{X_H}\omega = dH$	 <p>A diagram showing a horizontal line with a central point. Several concentric, roughly elliptical closed curves are drawn around the center. Arrows on these curves indicate a counter-clockwise direction of flow, representing periodic motion around a stable equilibrium point (a center).</p>
<p>More general case: given <math>H: M \rightarrow \mathbb{R}</math> and an antisymmetric <math>J(\mathbf{x})</math></p> $\dot{\mathbf{x}} = J(\mathbf{x}) \frac{\partial H}{\partial \mathbf{x}}$	<p>Poisson geometry</p> $\{\cdot, \cdot\} \text{ on } C^\infty(M)$ $X_H = \{H, \cdot\}$ $\dot{\mathbf{x}} = \{H, \mathbf{x}\}$	 <p>A photograph of a red spinning top resting on a light-colored wooden surface. The top has a conical body with horizontal ridges and a thin vertical stem. It is casting a shadow to the right.</p>

# History



## MÉCHANIQUE ANALITIQUE;

Par M. DE LA GRANGE, de l'Académie des Sciences de Paris,  
de celle de Berlin, de Pétersbourg, de Turin, &c.



A PARIS,  
Chez LA VEUVE DESAINT, Libraire,  
rue du Foix St. Jacques.  
M. DCC. LXXXVIII.  
AVEC APPROBATION ET PRIVILEGE DU ROI.

DÉPARTEMENT MATHÉMATIQUE  
Dirigé par le Professeur P. LE LONG

## STRUCTURE DES SYSTÈMES DYNAMIQUES

Maitrises de mathématiques

J.-M. SOURIAU  
Professeur de Physique Mathématique  
à la Faculté des Sciences de Montréal

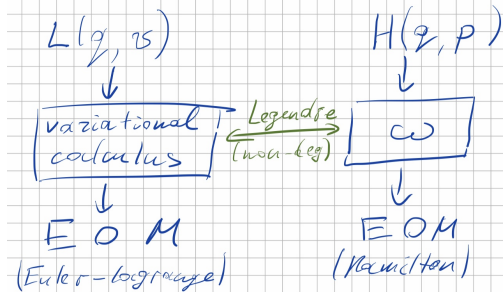
**DUNOD**  
PARIS  
1977



conférence de Jean-Pierre Bourguignon

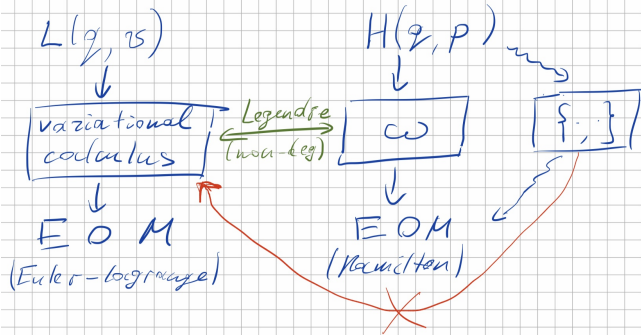
<https://www.youtube.com/watch?v=93hFolIBo0Q>

# Classical story in modern language

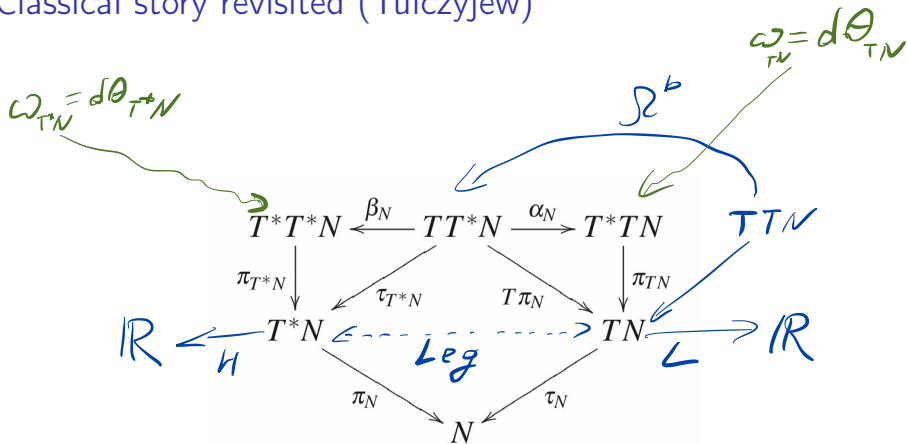




# Classical story in modern language



# Classical story revisited (Tulczyjew)



Rappel:  $T^*Q$ ,  $\omega = \sum_i p_i dq^i = d\left(\underbrace{\sum p_i q^i}_{\theta}\right)$

# Classical story revisited (Tulczyjew)

**4.3.5 Theorem** (W.M. Tulczyjew). *With the notations specified above (4.3.4), let  $X_H : T^*N \rightarrow TT^*N$  be the Hamiltonian vector field on the symplectic manifold  $(T^*N, d\theta_N)$  associated to the Hamiltonian  $H : T^*N \rightarrow \mathbb{R}$ , defined by  $i(X_H)d\theta_N = -dH$ . Then*

$$X_H(T^*N) = \beta_N^{-1}(dH(T^*N)).$$

*Moreover, the equality*

$$\alpha_N^{-1}(dL(TN)) = \beta_N^{-1}(dH(T^*N))$$

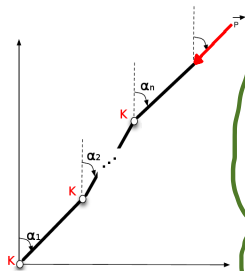
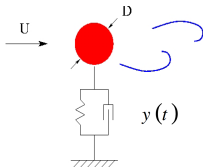
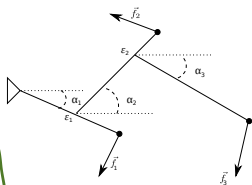
*holds if and only if the Lagrangian  $L$  is hyper-regular and such that*

$$dH = d(E_L \circ \mathcal{L}_L^{-1}),$$

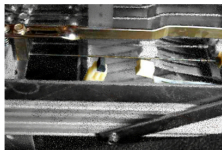
*where  $\mathcal{L}_L : TN \rightarrow T^*N$  is the Legendre map and  $E_L : TN \rightarrow \mathbb{R}$  the energy associated to the Lagrangian  $L$ .*

# Beyond: port-Hamiltonian systems; constraints

A lot of examples  
(ask Antoine Falaize, David Roze) :



Dirac structures



Conjecture (VS): Everything is port-Hamiltonian.

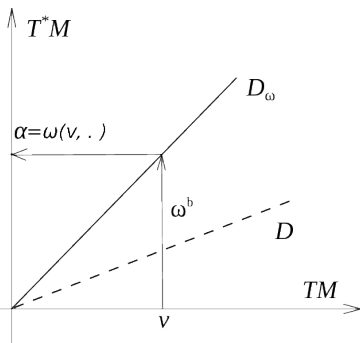
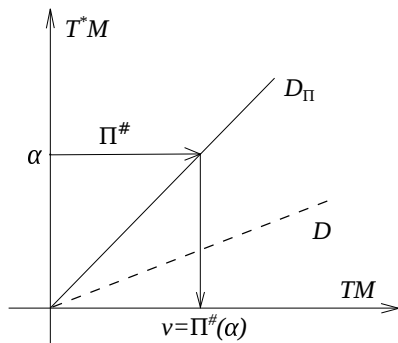
## Geometry behind: Courant algebroids, Dirac structures

On  $E = TM \oplus T^*M$  (or more generally  $F \oplus F^*$ )

Symmetric pairing:  $\langle v \oplus \eta, v' \oplus \eta' \rangle = \eta(v') + \eta'(v)$ ,

Dorfman bracket:  $[v \oplus \eta, v' \oplus \eta']_D = [v, v']_{\text{Lie}} \oplus (\mathcal{L}_v \eta' - d\eta(v'))$ .

A *Dirac structure*  $\mathcal{D}$  is a maximally isotropic (Lagrangian) subbundle of  $E$  closed w.r.t.  $[\cdot, \cdot]_D$

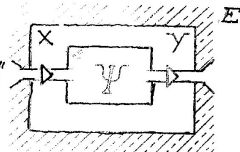


$$\mathcal{D}_\Pi = \text{graph}(\Pi^\#) = \{(\Pi^\# \alpha, \alpha)\}$$

$$\mathcal{D}_\omega = \text{graph}(\omega^b) = \{(v, \iota_v \omega)\}$$

# SYSTEMS ENGINEERING SEMINAR

"PORTS,  
ENERGY,  
SYSTEMS"



1959

Professor Henry M. Paynter will present a seminar on the subject, "Ports, Energy and Thermodynamic Systems" on Friday, April 24 at 3:15 p.m. in Room B 103 of the Mechanical Engineering Building.

Dr. Paynter is Assistant Professor of Mechanical Engineering at M.I.T. and Director of the American Center for Analog Computing (a facility of Pi-Square Engineering Company). He is prominently recognized for his work in controls, dynamic systems, analog simulation and related fields. He is the author of very many authoritative papers covering a wide range of topics. He has also done extensive consulting work in industry and government.

Dr. Paynter is a very interesting and stimulating speaker. His viewpoints are novel and thought-provoking.

– Henry M. Paynter, Analysis and Design of Engineering Systems, MIT Press, Cambridge, Massachusetts, 1961.

– Jean U. Thoma, Introduction to Bond Graphs and Their Applications, Pergamon Press, Oxford, 1975.

# Philosophy

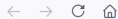
←	→	↺	🏠	🔒	<a href="https://math.ucr.edu/home/baez/week292.html">https://math.ucr.edu/home/baez/week292.html</a>
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	displacement $q$	flow $q'$	momentum $p$	effort $p'$
Mechanics (translation)	position	velocity	momentum	force
Mechanics (rotation)	angle	angular velocity	angular momentum	torque
Electronics	charge	current	flux linkage	voltage
Hydraulics	volume	flow	pressure momentum	pressure
Thermodynamics	entropy	entropy flow	temperature momentum	temperature
Chemistry	moles	molar flow	chemical momentum	chemical potential

( et Economie :) )

“This Week’s Finds in Mathematical Physics”, by John Baez

# Philosophy



<https://math.ucr.edu/home/baez/week292.html>

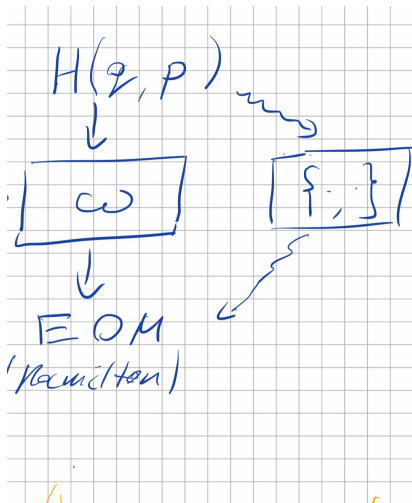
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Hydraulics	volume	flow	pressure momentum	pressure
Thermodynamics	entropy	entropy flow	temperature momentum	temperature
Chemistry	moles	molar flow	chemical momentum	chemical potential



J.-M. Souriau's thermodynamics,  
cf. also C.-M. Marle <https://arxiv.org/abs/1608.00103>



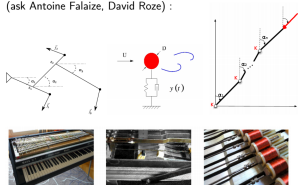
# What is the conceptual difference?



**Numerics (ask Anthony Gravouil)**

Beyond: port-Hamiltonian systems; constraints

A lot of examples  
(ask Antoine Falaize, David Roze) :

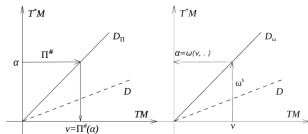


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$D_\Pi = \text{graph}(\Pi^\sharp) = \{(\Pi^\sharp \alpha, \alpha)\}$      $D_\omega = \text{graph}(\omega^\flat) = \{(v, \iota_v \omega)\}$

## Some directions

- Geometrical Mechanics on algebroids

K. Grabowska, J. Grabowski, P. Urbański,

<https://arxiv.org/abs/math-ph/0509063>

- Variational formulation of dynamics on Dirac structures,

J. O. Cosserat, C. Laurent-Gengoux, A. Kotov, L. Ryvkin.



## a bit of religion



Quarks  
 $SU(3)$  symmetry

$\Rightarrow \Rightarrow$   
 $\Rightarrow \Rightarrow$

G  
a  
u  
g  
i  
n  
g

$\Rightarrow \Rightarrow$   
 $\Rightarrow \Rightarrow$



8 connection 1-forms  
Gluons

# Methods from HEP



<b>Chapter One. Constrained Hamiltonian Systems</b>	<b>3</b>
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1.1.3. The Canonical Hamiltonian	9
1.1.4. Action Principle in Hamiltonian Form	11
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Important “tool”:  
graded geometry,  
differential graded  
manifolds.

# Graded manifolds – details

“...graded manifolds are just manifolds with a few bells and whistles...” (D. Roytenberg)

## Graded manifolds, super manifolds

### History



Felix Berezin



Joseph Bernstein



Pierre Deligne



Dimitry Leites

### Philosophy



Dmitry Roytenberg

“...graded manifolds are just manifolds with a few bells and whistles...”

## Graded geometry: definitions (do not read)

- Graded vector space  $V$  is a collection of vector spaces  $V = \oplus V_i$  ( $i \in \mathbb{Z}$  or  $i \in \mathbb{Z}_{\geq 0}$ ); if  $v \in V_i$ ,  $\deg(v) = i$ .
- Homomorphism shifting the grading by  $p$ :  $(V[p])_i = V_{i-p}$ .
- Assume the base to be of degree 0, the dual vector space  $(V_i)^*$  is defined as  $(V^*)_{-i}$ .
- Graded algebra structure  $\cdot: V \otimes V \rightarrow V$ , s.t.  $V_p \otimes V_q \rightarrow V_{p+q}$ .
- Graded commutator  $[a, b] = ab - (-1)^{\deg(a)\deg(b)}ba$ .
- Graded symmetric algebra over  $V$ :  $S(V) = \text{Tensor}(V)/[\cdot, \cdot]$

**Definition.** Graded manifold  $M$  is a couple  $(M_0, \mathcal{O}_M)$ , where  $M_0$  is a smooth manifold and the sheaf of functions  $\mathcal{O}_M$  is locally isomorphic to  $C^\infty(U_0) \otimes S(V)$ , where  $U_0$  is an open subset of  $M_0$ .

- Top degree of the generators of  $\mathcal{O}_M$  – is called degree of  $M$ .  
Standard abuse of notations:  $V_k$ -vector bundle or sheaf of sections.

## Graded manifolds

D. Roytenberg: “...bells and whistles...”

**Prop.** (D. Roytenberg) Given a non-negatively graded manifold  $(M, \mathcal{O}_M)$  there is a tower of fibrations

$$M = M_n \rightarrow M_{n-1} \rightarrow \cdots \rightarrow M_1 \rightarrow M_0,$$

where any  $M_k$  is a graded manifold of degree at most  $k$ , for  $k > 0$   
 $M_{k+1} \rightarrow M_k$  is an affine bundle.

**Remark.** Gradings can be encoded in the Euler vector field  
 $\epsilon = \deg(q^\alpha) q^\alpha \frac{\partial}{\partial q^\alpha}$ ;  $V_i$  corresponds to the  $i$ -eigenspace of  $\epsilon$ .

**Remark.** Gradings can be encoded in the homogeneity structure  
 $h: \mathbb{R}_+ \times \mathcal{M} \rightarrow \mathcal{M}$  such that  
 $(q^1, \dots, q^N) \mapsto h_t(q^1, \dots, q^N) \equiv (t^{\deg(q^1)} q^1, \dots, t^{\deg(q^N)} q^N).$

For graded good

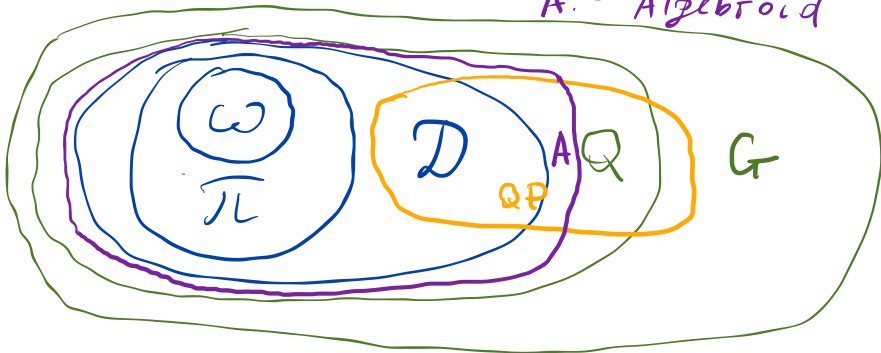
$G :=$  Graded

$Q :=$  Differential Graded

$QP :=$  DG symplectic

$A :=$  Algebroid

– “Folkloric” applications in geometry



– Other applications (in mechanics?):

A. Bruce, K. Grabowska, J. Grabowski, Higher order mechanics on graded bundles <https://arxiv.org/abs/1412.2719>

## Derived bracket construction

Let  $(\mathcal{M}, Q)$  be a  $Q$ -manifold (i.e. graded manifold with a degree 1 homological vector field  $Q$ ), and

$\mathcal{G}$  be degree  $-1$  vector fields  $\varepsilon$  on  $\mathcal{M}$ .

Define the  $Q$ -derived bracket:  $[\varepsilon, \varepsilon']_Q := [\varepsilon, [Q, \varepsilon']]$ .

**Remark.** Good for equivariant  $Q$ -cohomology.

V.S. “Graded geometry in gauge theories and beyond”, JGP, 2015.

**Example 1.**  $(T^*[1]M, Q_\pi)$

$$\varepsilon = \varepsilon_i(x) \frac{\partial}{\partial p_i} \leftrightarrow \varepsilon_i(x) dx^i \in \Omega^1(M).$$

If  $\varepsilon$  is exact, i.e.  $\varepsilon_i dx^i = \epsilon_{,i} dx^i$ , then  $[\varepsilon, \varepsilon']_Q = \{\epsilon, \epsilon'\}_{,i} \frac{\partial}{\partial p_i}$

**Example 2.** Dirac structures.

# Equivariant cohomology and gauging in a nutshell

“equations of motion”	$\leftrightarrow$	$Q$ -morphisms
“symmetries”	$\leftrightarrow$	$Q$ -homotopies
“gauge invariant”	$\leftrightarrow$	“equivariantly $Q$ -closed”

**Example: Dirac sigma model** – functional on vector bundle morphisms from  $T\Sigma$  to  $\mathcal{D}$ .

$$S_{DSM} = \int_{\Sigma} g(dX, \wedge (1 + \mathcal{O})A) + g(A, \wedge \mathcal{O}A) + \int_{\Sigma_3} H.$$

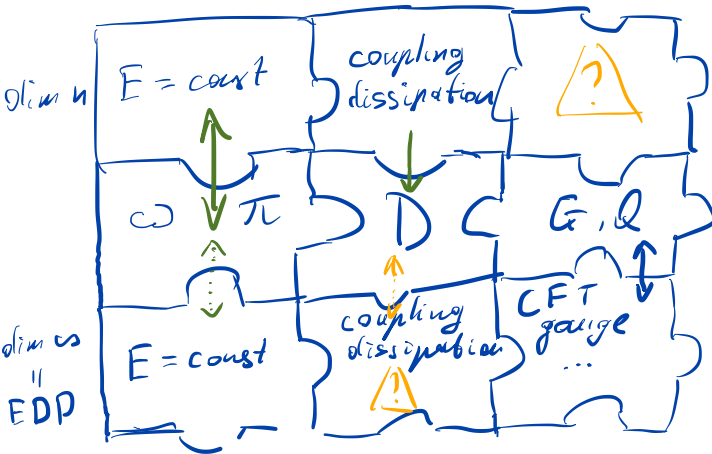
**Theorem.** The algebra of infinitesimal gauge transformations is given by smooth maps  $\Sigma \rightarrow \Gamma(\mathcal{D})$ , subject to  $d\eta - \iota_v H = 0$ . (\*)  
Conversely, DSM is obtained by gauging of an extension of (\*).

**Theorem.** DSM is the most general theory obtained by gauging the Wess-Zumino term in space-time dimension 2.

- V.S., T.Strobl, “Dirac Sigma Models from Gauging”, JHEP, 2013.
- A.Kotov, V.S., T.Strobl, “2d Gauge theories and generalized geometry”, JHEP, 08, 2014.



Instead of conclusion – big puzzle and questions



And what precisely about mechanics? What phenomena?

→ Thermo de Souriau (resp. Hamdani de Sarkis)

→ Galois de Vinogradov (resp. Roubtsov)