

Thermodynamique pentadimensionnelle des milieux continus

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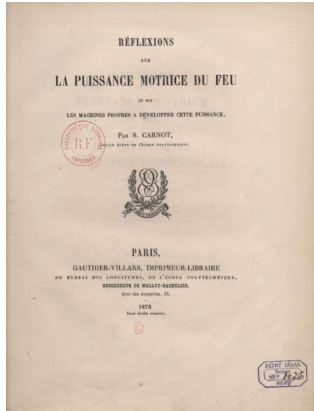
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Bicentenary of the Thermodynamics



Relativity and Thermodynamics



General Relativity

a **model** for the mechanics and physics of continua

- Temperature \longrightarrow vector W
- Entropy \longrightarrow vector S
- Energy \longrightarrow tensor T
- Gravitation \longrightarrow covariant derivative ∇

State of the Art

- Background

C Eckart, Phys. Rev. (1940) $\operatorname{div} T = 0$ (1st principle)

Landau-Lifshitz, Fluid Mech. (1960) $T = T_R + T_I, \quad S = T W$

- Inspiration sources

JM Souriau, Lect. Notes Math. (1976) $\operatorname{div} S \geq 0$ (2nd principle)

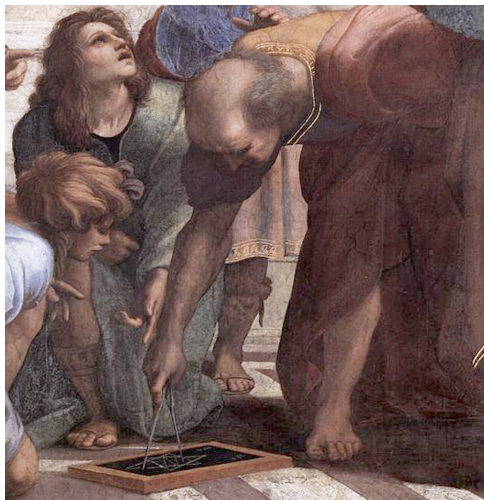
C Vallée, IJES (1981) constitutive laws

- The present contribution

de Saxcé-Vallée, IJES (2012) Galilean version

de Saxcé-Vallée, Galilean Mechanics and Thermodynamics of Continua (2016) revisiting the relativistic version of the 2nd principle

Geometric approach



Galilean transformations

- Event occurring at position x and at time t

$$X = \begin{pmatrix} t \\ x \end{pmatrix} \in \text{space-time } \mathcal{M}$$

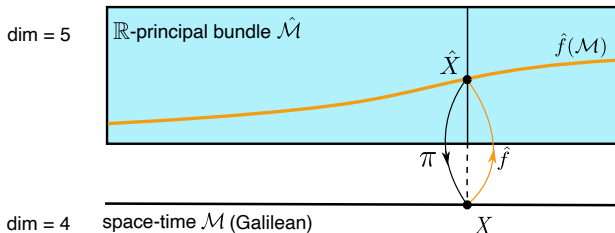
- **Symmetry group** : Lorentz-Poincaré group \longrightarrow Galileo's group
- The **Galilean transformations** are space-time transformations preserving **inertial motions**, **durations** and **distances**, then affine of the form $X = P X' + C$ with :

$$P = \begin{pmatrix} 1 & 0 \\ v_t & R \end{pmatrix}, \quad C = \begin{pmatrix} \tau_0 \\ k \end{pmatrix}$$

where $v_t \in \mathbb{R}^3$ is the **Galilean boost** and R is a rotation

- Their set is **Galileo's group**, a Lie group of dimension 10
- **Dimension 4 or 5?**

Bargmannian transformations



- We introduce a **\mathbb{R} -principal bundle** $\pi : \hat{\mathcal{M}} \rightarrow \mathcal{M}$ and we consider a **section** $\hat{f} : \mathcal{M} \rightarrow \hat{\mathcal{M}} : \mathbf{X} \mapsto \hat{\mathbf{X}} = \hat{f}(\mathbf{X})$
- We built a group of affine transformations $\hat{X}' \mapsto \hat{X} = \hat{P} \hat{X}' + \hat{C}$ of \mathbb{R}^5 which are Galilean when acting onto the space-time hence :

$$\hat{P} = \begin{pmatrix} P & 0 \\ \Phi & \alpha \end{pmatrix},$$

where P is Galilean, Φ, α have a physical meaning linked to the energy

Bargmannian transformations

- Thus we know that, under the action of a boost v_t and a rotation R , the kinetic energy is transformed according to :

$$e = \frac{1}{2} m \| v_t + R v' \|^2 = \frac{1}{2} m \| v_t \|^2 + m v_t \cdot (R v') + \frac{1}{2} m \| v' \|^2 .$$

- We claim that the fifth dimension is linked to the energy by :

$$dz = \frac{e}{m} dt = \frac{1}{2} \| v_t \|^2 dt' + v_t^T R dx' + dz'$$

that leads to consider the **Bargmannian transformations** of \mathbb{R}^5

of which the linear part is : $\hat{P} = \begin{pmatrix} 1 & 0 & 0 \\ v_t & R & 0 \\ \frac{1}{2} \| v_t \|^2 & v_t^T R & 1 \end{pmatrix}$

Their set is the **Bargmann's group**,
introduced in quantum mechanics for cohomologic reasons
but which turns out very useful in Thermodynamics !

Temperature, friction and momentum tensor



Temperature 5-vector

The reciprocal temperature $\beta = \frac{1}{\theta} = \frac{1}{k_B T}$ is generalized as a Bargmannian 5-vector :

$$\hat{W} = \begin{pmatrix} W \\ \zeta \end{pmatrix} = \begin{pmatrix} \beta \\ w \\ \zeta \end{pmatrix},$$

Step 1 :

- The transformation law $\hat{W}' = \hat{P}^{-1} \hat{W}$ leads to :

$$\beta' = \beta, \quad w' = R^T(w - \beta v_t), \quad \zeta' = \zeta - w \cdot v_t + \frac{\beta}{2} \|v_t\|^2$$

- Picking up $v_t = w / \beta$, we obtain the **reduced form**

$$\hat{W}' = \begin{pmatrix} \beta \\ 0 \\ \zeta_{int} \end{pmatrix}$$

interpreted as the temperature vector of a volume element **at rest**

Temperature 5-vector

Step 2 : Starting from the reduced form, we apply the Galilean transformation of boost v , that gives :

$$\hat{W} = \begin{pmatrix} \beta \\ w \\ \zeta \end{pmatrix} = \begin{pmatrix} \beta \\ \beta v \\ \zeta_{int} + \frac{\beta}{2} \|v\|^2 \end{pmatrix} .$$

where ζ is **Planck's potential**

This is the covariant form of the temperature vector, *i.e.* remaining the same under all Galilean transformation

Boost method :

- **Step 1** : symmetry group action \longrightarrow reduced form
- **Step 2** : boost \longrightarrow covariant form

Friction tensor

Friction tensor

The **friction tensor** is a mixed 1-covariant and 1-contravariant tensor :

$$f = \nabla \vec{W}$$

represented by the 4×4 matrix $f = \nabla W$

- This object introduced by Souriau merges the temperature gradient and the strain velocity
- In dimension 5, we can also introduce

$$\hat{f} = \nabla \hat{W}$$

represented by a 5×4 matrix

$$\hat{f} = \nabla \hat{W} = \begin{pmatrix} f \\ \nabla \zeta \end{pmatrix}$$

Momentum tensor

Method

Taking care **to walk up and down the rough ground of the reality** (Wittgenstein),

we want to work, in dimension 4 ou 5, with tensors of which the transformation law respects the physics



The meaning of the components is not given *a priori* but results, through the transformation law, from the choice of the symmetry group

Momentum tensor

Momentum tensor

Linear map from the tangent space to $\hat{\mathcal{M}}$ at $\hat{\mathbf{X}} = \hat{f}(\mathbf{X})$ into the tangent space to \mathcal{M} at \mathbf{X} , hence a **mixed tensor** $\hat{\mathbf{T}}$ of rank 2

- **Galilean momentum tensors** : represented by a 4×5 matrix

$$\hat{\mathbf{T}} = \begin{pmatrix} \mathcal{H} & -\rho^T & \rho \\ k & \sigma_* & p \end{pmatrix}$$

In matrix form, the transformation law is $\hat{\mathbf{T}}' = P \hat{\mathbf{T}} \hat{P}^{-1}$

- **We let the symmetry group act**, that leads to the **reduced form** :

$$\hat{\mathbf{T}}' = \begin{pmatrix} \rho e_{int} & 0 & \rho \\ h & \sigma & 0 \end{pmatrix},$$

interpreted as the momentum of a volume element **at rest**, where occur the **density** ρ , the **internal energy** e_{int} , the **heat flux** h , and **Cauchy's stresses** σ

Momentum tensor

Hence the **boost method** reveals its **covariant form**

Galilean momentum tensor

Object where occurs

- **Hamiltonian** (by volume unit) $\mathcal{H} = \rho \left(e_{int} + \frac{1}{2} \|v\|^2 \right)$
- **linear momentum** $p = \rho v$,

represented by the matrix :

$$\hat{T} = \begin{pmatrix} \mathcal{H} & -p^T & \rho \\ h + \mathcal{H} v - \sigma v & \sigma - \rho v v^T & p \end{pmatrix}$$

These particular quantities are gathered here in big tensors

First and second principles



First principle

Momentum divergence

5-row $div \hat{T}$ such that, for all smooth 5-vector field \hat{W} :

$$Div (\hat{T} \hat{W}) = (Div \hat{T}) \hat{W} + Tr (\hat{T} \nabla \hat{W})$$

Covariant form of the 1st principle

$$Div \hat{T} = 0$$

First principle

In absence of gravity, we recover the balance equations of :

- mass : $\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \mathbf{v}) = 0$
- linear momentum : $\rho \left[\partial_t \mathbf{v} + \frac{\partial \mathbf{v}}{\partial x} \mathbf{v} \right] = (\operatorname{div} \sigma)^T$
- energy : $\partial_t \mathcal{H} + \operatorname{div}(h + \mathcal{H} \mathbf{v} - \sigma \mathbf{v}) = 0$

First principle

$$\text{4-velocity } U = \frac{dX}{dt} = \frac{d}{dt} \begin{pmatrix} t \\ x \end{pmatrix} = \begin{pmatrix} 1 \\ v \end{pmatrix}$$

Reversible medium

if ζ is a function of

- the other components of \hat{W} through W ,
- the right Cauchy strain $C = F^T F$
- and the Lagrangean coordinates,

then the 4×4 matrix $T_R = U \otimes \Pi_R + \begin{pmatrix} 0 & 0 \\ -\sigma_{RV} & \sigma_R \end{pmatrix}$

$$\text{with } \Pi_R = -\rho \frac{\partial \zeta}{\partial W} \quad \sigma_R = -\frac{2\rho}{\beta} F \frac{\partial \zeta}{\partial C} F^T$$

is such that :

$$\heartsuit \hat{T}_R = \begin{pmatrix} T_R & N \end{pmatrix} \text{ with } N = \rho U \text{ represents a momentum tensor } \hat{T}_R$$

$$\diamondsuit \text{Tr} \left(\hat{T}_R \nabla \hat{W} \right) = 0$$

First principle

ζ is the prototype of **thermodynamic potentials** :

- the **internal energy** $e_{int} = -\frac{\partial \zeta_{int}}{\partial \beta}$

- the **specific entropy** $s = \zeta_{int} - \beta \frac{\partial \zeta_{int}}{\partial \beta}$

of which the 4-flux $\vec{S} = s \vec{N}$ is the Galilean 4-vector

$$\vec{S} = \hat{T}_R \hat{W}$$

- the **free energy** $\psi = -\frac{1}{\beta} \zeta_{int} = -\theta \zeta_{int}$ allows to recover
 $-e_{int} = \theta \frac{\partial \psi}{\partial \theta} - \psi, \quad -s = \frac{\partial \psi}{\partial \theta}$

The interest of Planck's potential ζ is that it generates all the other ones

Second principle

Additive decomposition of the momentum tensor

$$\hat{T} = \hat{T}_R + \hat{T}_I \text{ with}$$

- the reversible part \hat{T}_R represented by :

$$\hat{T}_R = \begin{pmatrix} \mathcal{H}_R & -p^T & \rho \\ \mathcal{H}_{RV} - \sigma_{RV} & \sigma_R - vp^T & \rho v \end{pmatrix}$$

- the irreversible one \hat{T}_I represented by :

$$\hat{T}_I = \begin{pmatrix} \mathcal{H}_I & 0 & 0 \\ h + \mathcal{H}_{IV} - \sigma_{IV} & \sigma_I & 0 \end{pmatrix}$$

where σ_I are the **dissipative stresses** and $\mathcal{H}_I = -\rho q_I$ is the dissipative part of the energy due to the **irreversible heat sources** q_I (for instance of electrical, chemical or nuclear origin)

Second principle

Clock form

Linear form $\tau = dt$ represented by an invariant row under Galilean transformation :

$$\tau = (1 \quad 0 \quad 0 \quad 0)$$

Entropy 4-vector $\vec{S} = \hat{T} \hat{W} = \hat{T}_R \hat{W} + \hat{T}_I \hat{W} = \vec{S}_R + \vec{S}_I$

Covariant form of the second principle

The **local production of entropy** of a medium characterized by a temperature vector \hat{W} and a momentum tensor \hat{T} is non negative :

$$\Phi = \text{Div } \vec{S} - \left(\tau(\mathbf{f}(\vec{U})) \right) \left(\tau(\mathbf{T}_I(\vec{U})) \right) \geq 0$$

and vanishes if and only if the process is reversible

Second principle

- The local production of entropy

$$\Phi = \mathbf{Div} \vec{S} - \left(\tau(\mathbf{f}(\vec{U})) \right) \left(\tau(\mathbf{T}_I(\vec{U})) \right)$$

is a **Galilean invariant** !

- After some manipulations, it can be put in the classical form of **Clausius-Duhem inequality**

$$\Phi = \rho \frac{ds}{dt} - \frac{\rho}{\theta} \frac{dq_I}{dt} + \mathit{div} \left(\frac{h}{\theta} \right) \geq 0$$

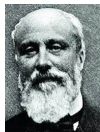
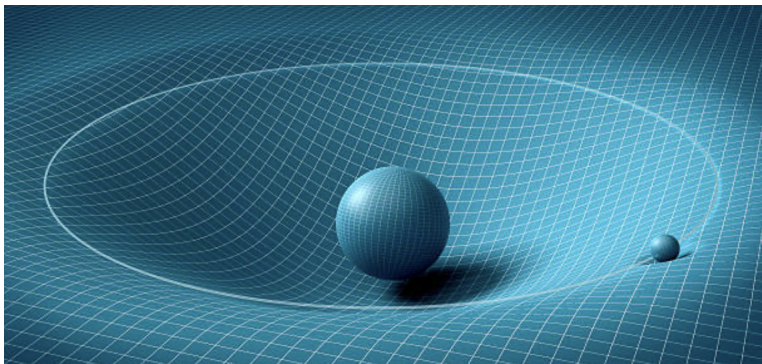
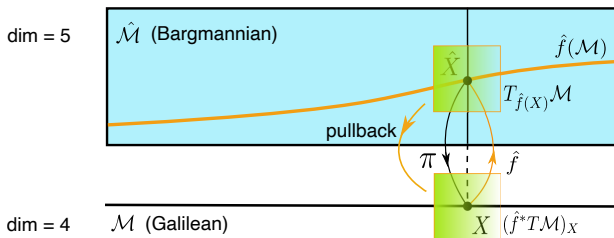


FIGURE – Pierre Duhem

Thermodynamics and Galilean gravitation



Thermodynamics and Galilean gravitation



- We consider the pullback bundle $\hat{f}^* T\hat{\mathcal{M}}$
- The space-time \mathcal{M} is endowed with the pullback connection $(\hat{f}^*\hat{\nabla})_{\mathbf{U}}(\hat{f}^*\hat{\mathbf{W}}) = \hat{f}^*(\hat{\nabla}_{(Tf)\mathbf{U}}\hat{\mathbf{W}})$ $\mathbf{U} \in T\mathcal{M}$, $\hat{\mathbf{W}} \in T\hat{\mathcal{U}}$
- Galileo's group does not preserve space-time metrics
- Bargmann's group preserves the metrics $ds^2 = \|dx\|^2 - 2dz dt$, then the space $\hat{\mathcal{M}}$ is a riemannian manifold

Thermodynamics and Galilean gravitation

- With the **potentials of the Galilean gravitation** ϕ , \mathbf{A} generating the gravity $\mathbf{g} = -\text{grad } \phi - \partial_t \mathbf{A}$ and Coriolis effect $\boldsymbol{\Omega} = \frac{1}{2} \text{curl } \mathbf{A}$, the Lagrangian is $\mathcal{L}(t, \mathbf{x}, \mathbf{v}) = \frac{1}{2} m \|\mathbf{v}\|^2 - m\phi + m\mathbf{A} \cdot \mathbf{v}$

- that suggests to introduce a base change

$$dz' = \frac{\mathcal{L}}{m} dt = dz - \phi dt + \mathbf{A} \cdot d\mathbf{x}, \quad dt' = dt, \quad d\mathbf{x}' = d\mathbf{x}$$

- In the new coordinates, the **Bargmannian connection** is

$$\hat{\Gamma}(d\hat{X}) = \begin{pmatrix} 0 & 0 & 0 \\ j(\boldsymbol{\Omega}) d\mathbf{x} - \mathbf{g} dt & j(\boldsymbol{\Omega}) dt & 0 \\ ((\partial_t \phi - \mathbf{A} \cdot \mathbf{g}) dt + (\text{grad } \phi - \boldsymbol{\Omega} \times \mathbf{A}) \cdot d\mathbf{x}) & ((\text{grad } \phi - \boldsymbol{\Omega} \times \mathbf{A}) dt - \text{grad}_s \mathbf{A} dx)^T & 0 \end{pmatrix}$$

- As in electromagnetism, the potentials ϕ , \mathbf{A} are defined modulo a gauge transformation. It can be shown that it corresponds to a change of section \hat{f} then **the choice of the section does not modify the equations of Thermodynamics.**

Thermodynamics and Galilean gravitation

The developments are similar to the ones in absence of gravitation but with some exceptions :

- Planck's potential becomes $\zeta = \zeta_{int} + \frac{\beta}{2} \| \mathbf{v} \|^2 - \beta \phi + \mathbf{A} \cdot \mathbf{w}$
- the Hamiltonian becomes $\mathcal{H} = \rho \left(e_{int} + \frac{1}{2} \| \mathbf{v} \|^2 + \phi - q_I \right)$,
- the linear momentum becomes $\mathbf{p} = \rho (\mathbf{v} + \mathbf{A})$.

In presence of gravitation, the first principle provides **in covariant form** the balance equations of the mass and of

- the linear momentum : $\rho \frac{d\mathbf{v}}{dt} = (\text{div } \boldsymbol{\sigma})^T + \rho (\mathbf{g} - 2 \boldsymbol{\Omega} \times \mathbf{v})$
- the energy : $\partial_t \mathcal{H} + \text{div} (h + \mathcal{H}\mathbf{v} - \boldsymbol{\sigma}\mathbf{v}) = \rho (\partial_t \phi - \partial_t \mathbf{A} \cdot \mathbf{v})$

A smidgen of relativistic Thermodynamics

- **Epistemological reversal** : we come back to the relativity with **Lorentz-Poincaré** symmetry group
- In this approach, the temperature is transformed according to

$$\theta' = \frac{\theta}{\gamma} = \theta \sqrt{1 - \frac{\|v\|^2}{c^2}}$$

This the **temperature contraction** !

- thanks to the space-time Minkowski's metrics $ds^2 = c^2 dt^2 - \|dx\|^2$, we can associate to the 4-velocity \vec{U} a unique linear form U^* represented by

$$U^T G = \left(\gamma, \gamma v^T \right) \begin{pmatrix} c^2 & 0 \\ 0 & -1_{\mathbb{R}^3} \end{pmatrix} = c^2 \left(\gamma, -\frac{1}{c^2} \gamma v^T \right),$$

which approaches $c^2 \tau$ when c approaches $+\infty$

A smidgen of relativistic Thermodynamics

On this ground, we replace τ by \mathbf{U}^*/c^2 in the Galilean expression of Clausius-Duhem inequality, that lead to

Relativistic form of the 2nd principle

The **local production of entropy** of a medium characterized by a temperature vector \vec{W} and a momentum tensor \hat{T} is non negative :

$$\Phi = \text{Div } \vec{S} - \frac{1}{c^2} \left(\mathbf{U}^*(\mathbf{f}(\vec{U})) \right) - \frac{1}{c^2} \left(\mathbf{U}^*(\mathbf{T}_I(\vec{U})) \right) \geq 0 ,$$

and vanishes if and only if the process is reversible

$$\phi = \nabla_{\alpha} S^{\alpha} - \frac{1}{c^2} f_{\alpha\beta} U^{\alpha} U^{\beta} - \frac{1}{c^2} T_{I\alpha\beta} U^{\alpha} U^{\beta} \geq 0$$

The scheme of General Relativity is still valid in classical Mechanics

$$\phi = \nabla_{\alpha} S^{\alpha} - \frac{1}{c^2} f_{\alpha\beta} U^{\alpha} U^{\beta} - \frac{1}{c^2} T_{I\alpha\beta} U^{\alpha} U^{\beta} \geq 0$$

Thank you !

